

# Unsupervised Learning

– A Brief Introduction –

Christoph Schnörr

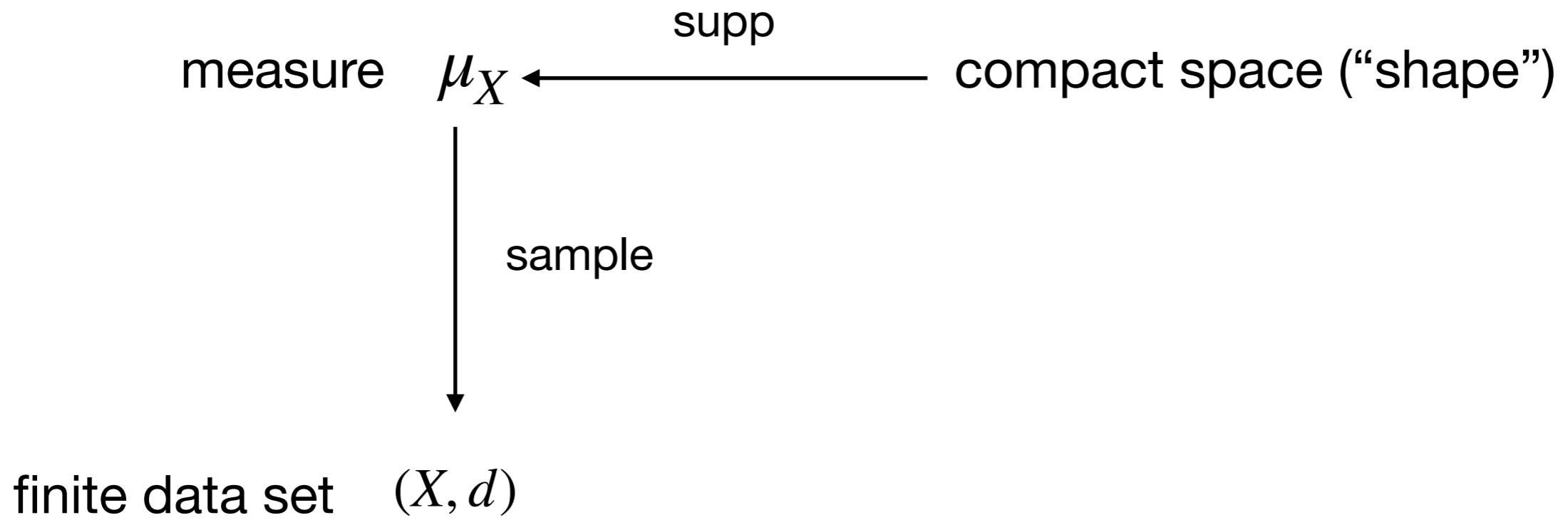
Image & Pattern Analysis Group  
Heidelberg University

STRUCTURES

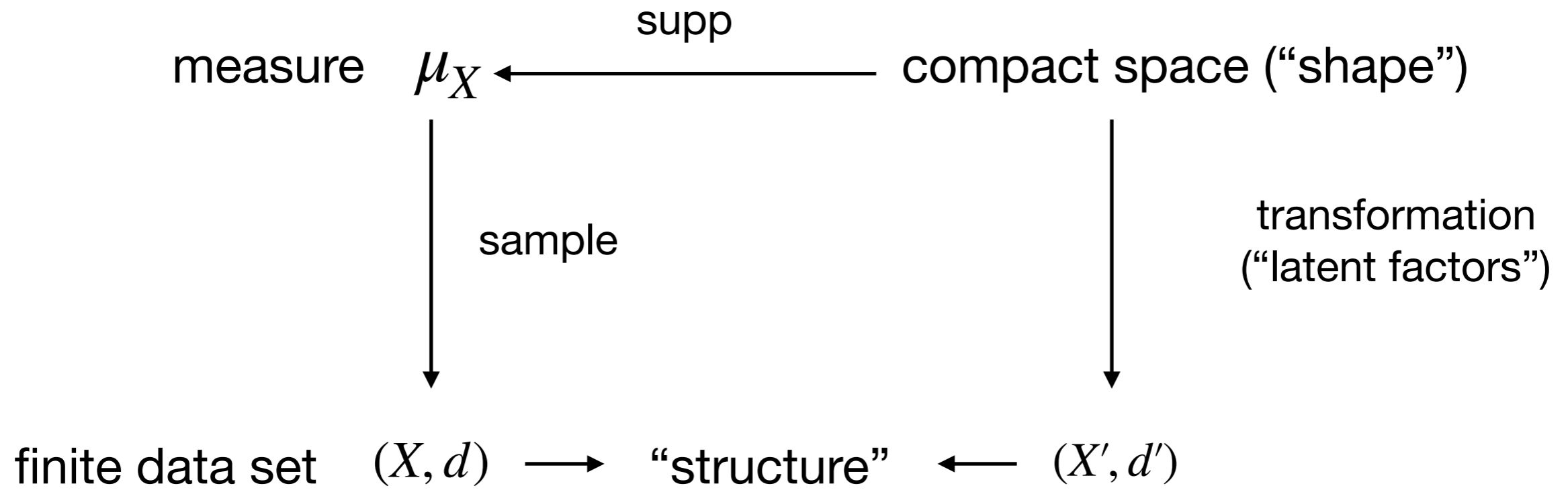
EP Mathematical Data Analysis

April 9, 2019

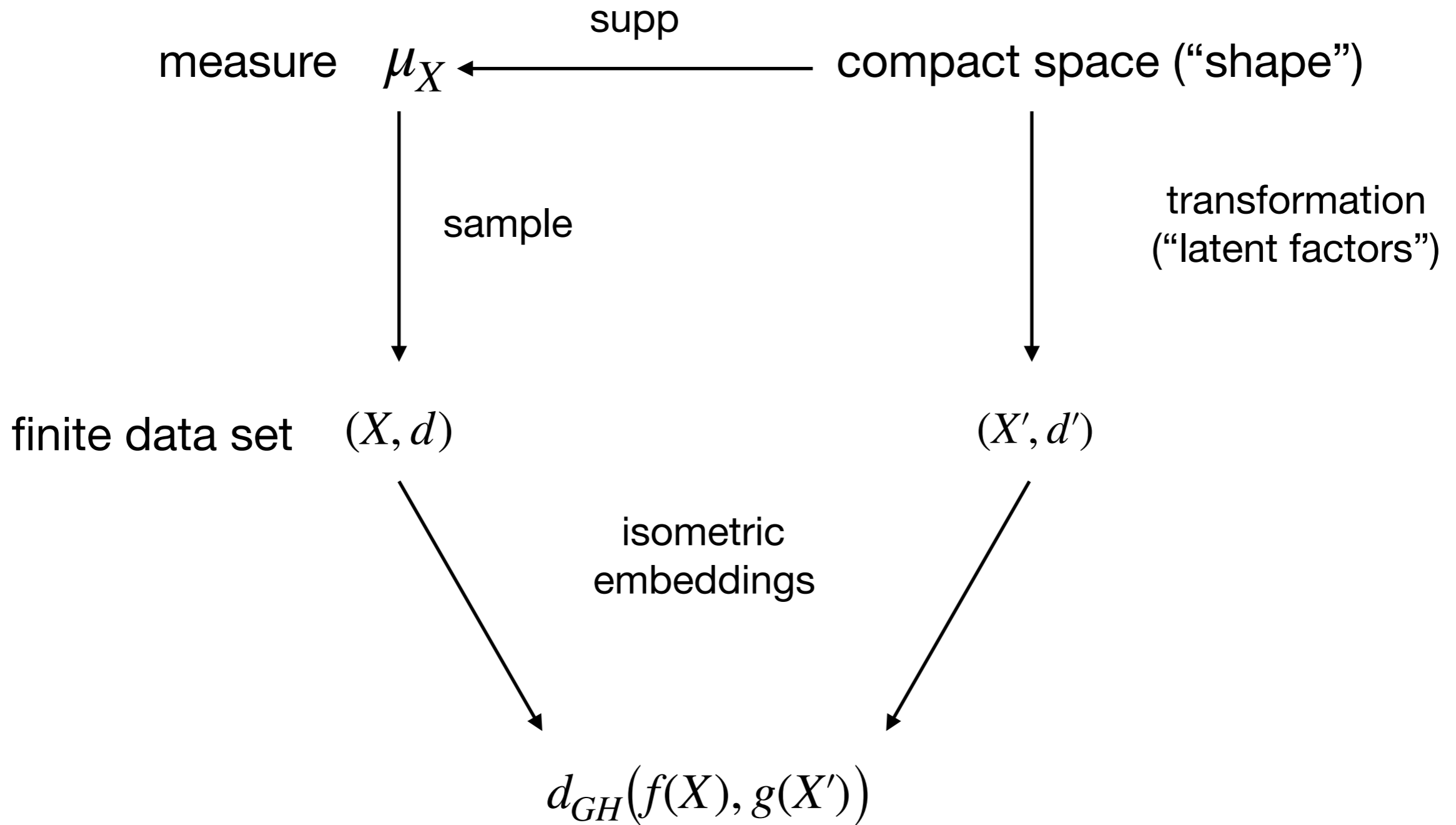
# Setting, Basic Task



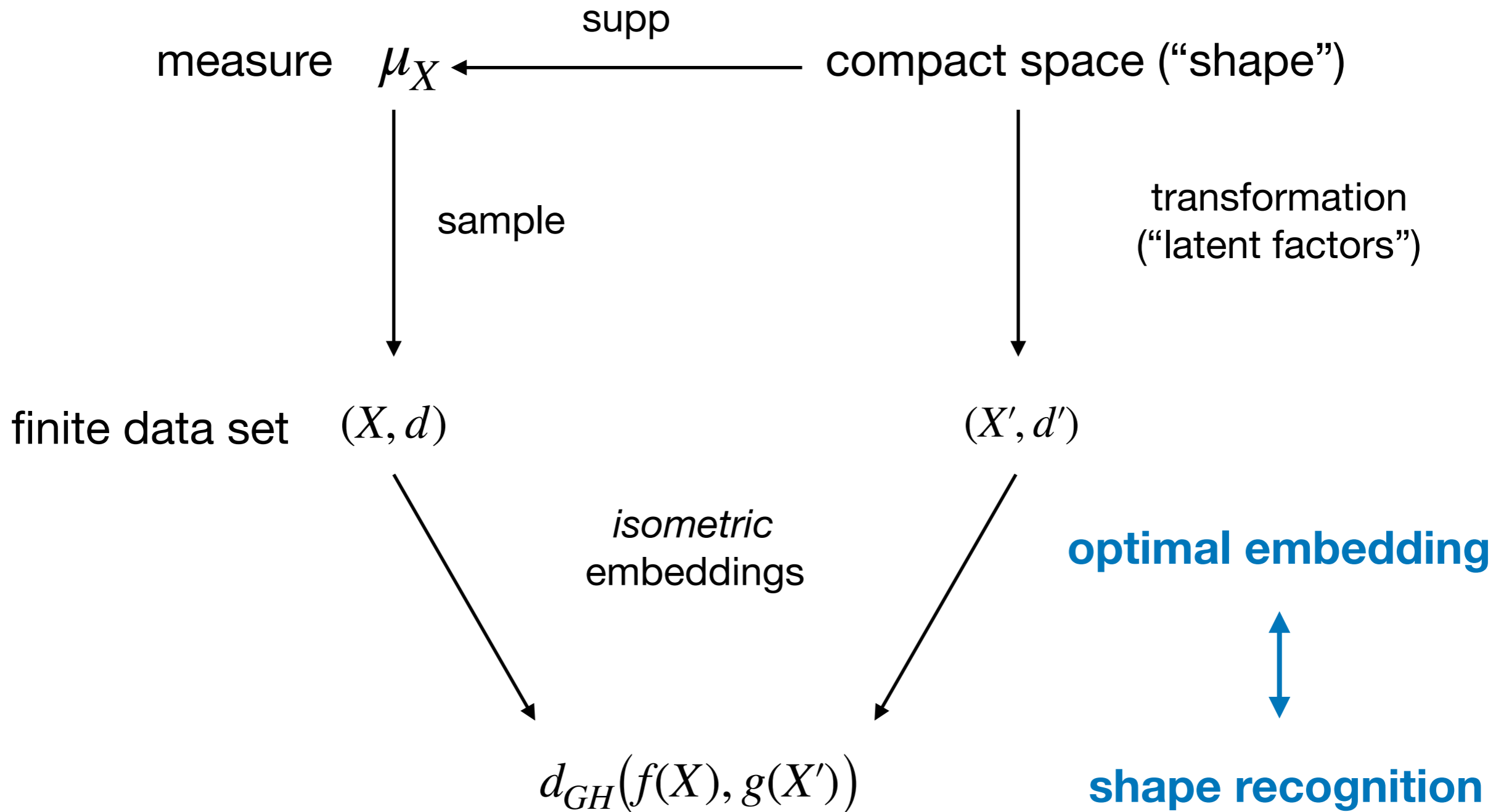
# Setting, Basic Task



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# Setting, Basic Task



# Data Representation

finite data set  $(X, d_X)$



embedding  
(distortion)

$\ell_2^n$   $\ell_2$   $\ell_p^n$   $(Y, d_Y)$

Euclidean  
Hilbert  
Banach  
metric

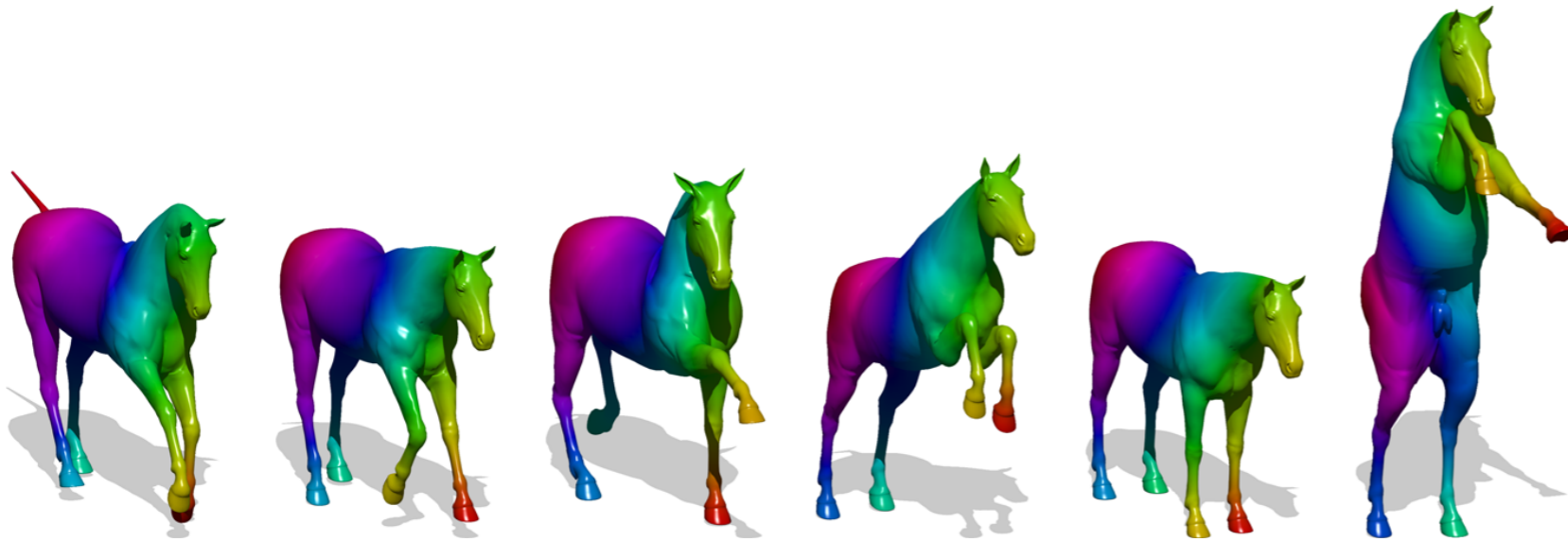


tasks

shape classification & recognition  
taming combinatorial optimization  
efficient distance oracles  
visualisation  
...

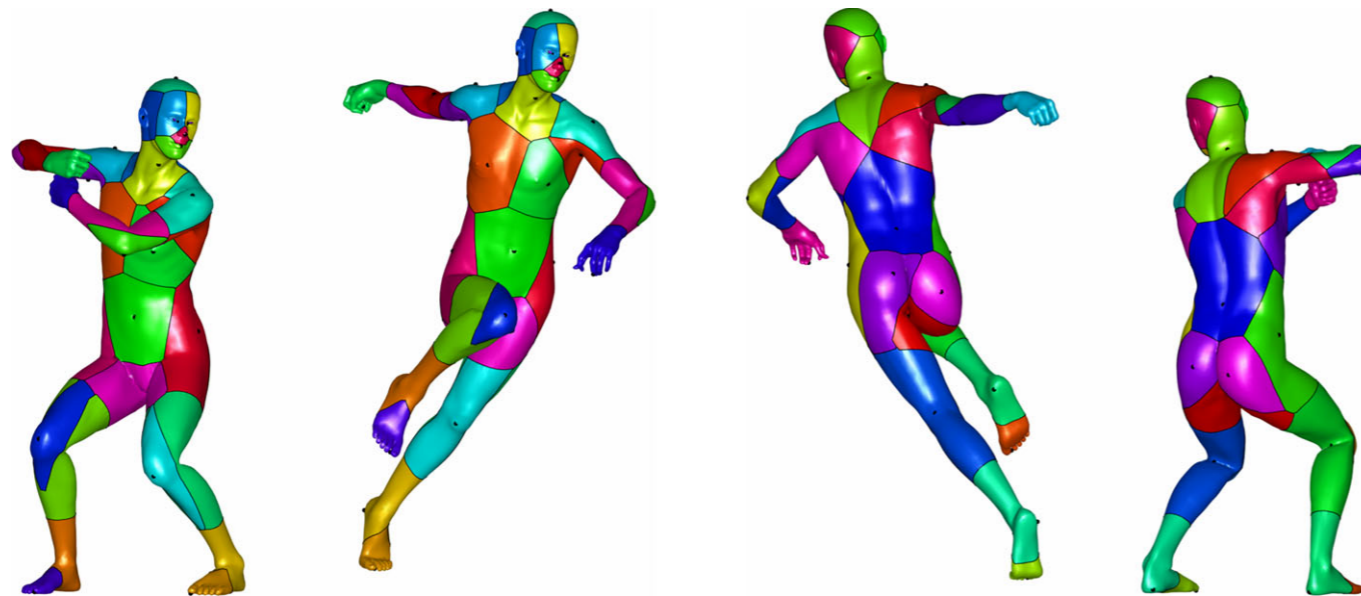
# Example, Manifold Assumption

*(Kimmel et al.  
IJCV'16)*

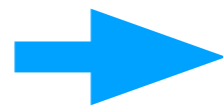


**good metric**

**clustering  
(partitioning, coding)**



# Manifold Assumption ?



stratified spaces  
("union of subspaces model")



# Manifold Assumption ?



# Outline

embedding



basic clustering  
(ignoring context)

metric  
Euclidean, Hilbert

(representative  
examples)

preliminary remark on TDA



clustering  
(context sensitive)

# Metric Embedding (I)

$$(X, d) \longrightarrow (X, d_{\mathcal{T}})$$

$d_T$  dominates  $d$ ,  $\forall T \in \mathcal{T}$

$$\mathbb{E}_P[d_T(u, v)] \leq \alpha d(u, v), \quad \forall u, v \in X$$

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clustering



$$E_{\infty}^* = \min_M E_{\infty}(M),$$

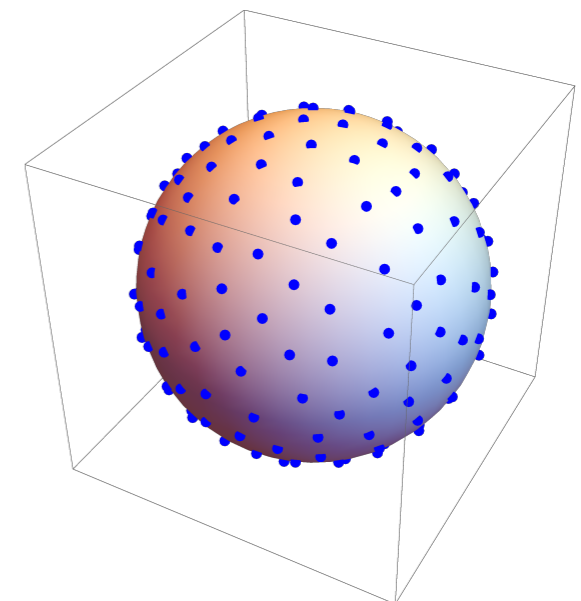
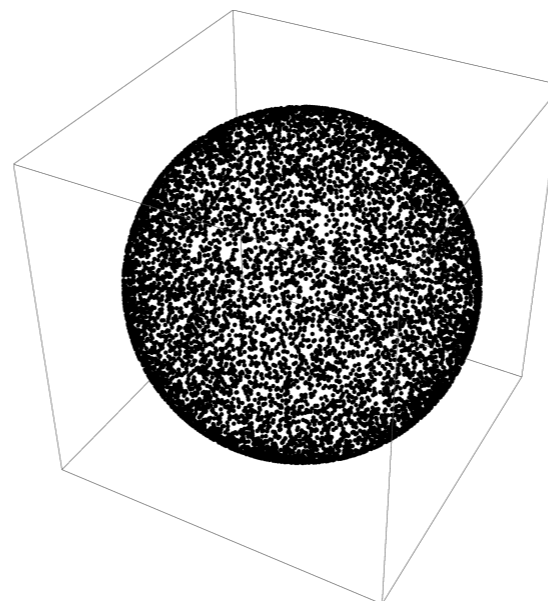
$$E_{\infty}(M) = \max_{x \in X} d(x, M)$$

$$E_{\infty}(M) \leq 2E_{\infty}^*$$

$$M = \{m^1, \dots, m^c\} \subset X$$

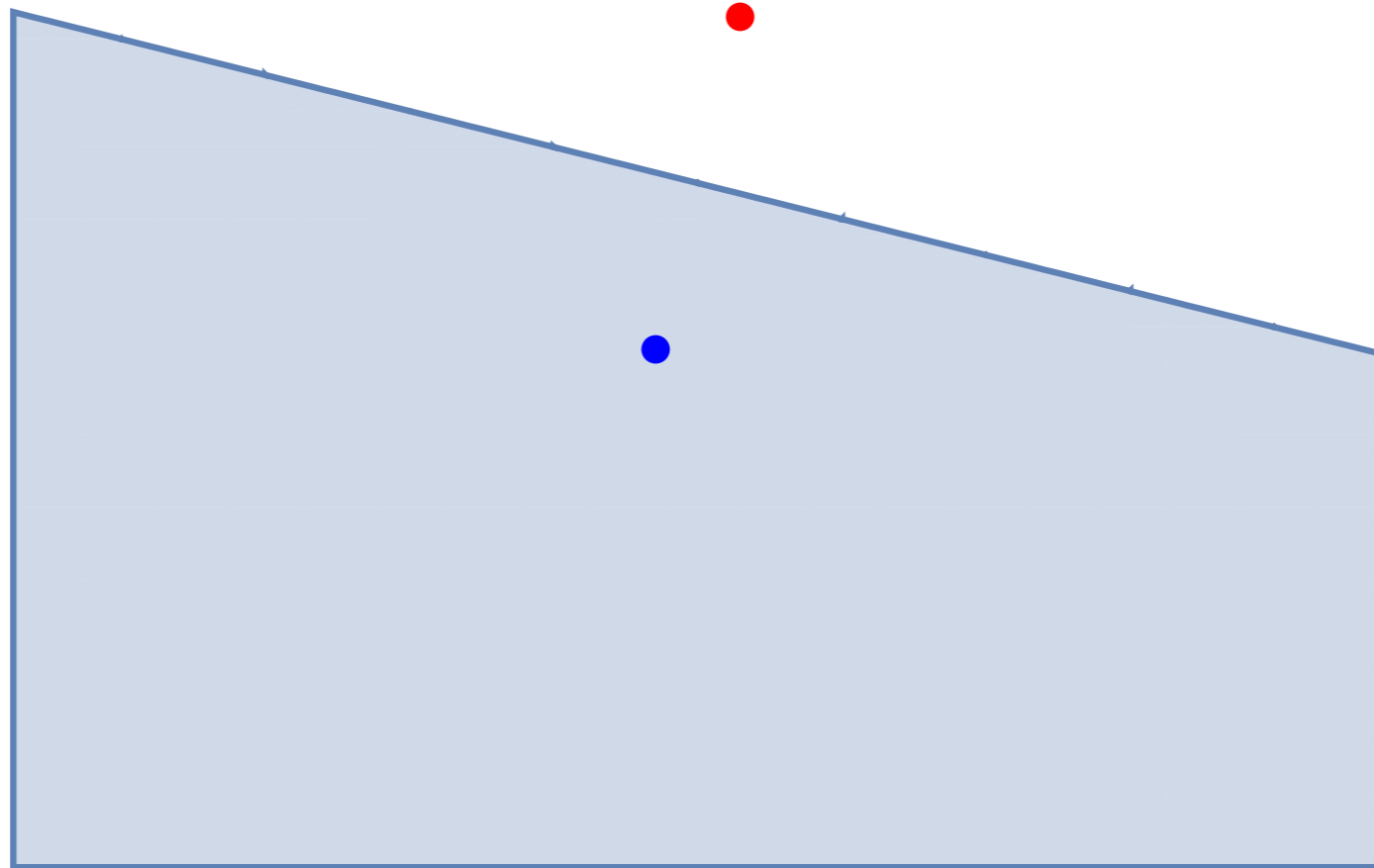
“core set”  
initialization for more  
advanced techniques

*any metric  
global method*



# Metric Embedding (II)

data, labels, prior beliefs



## Metric Embedding (II)

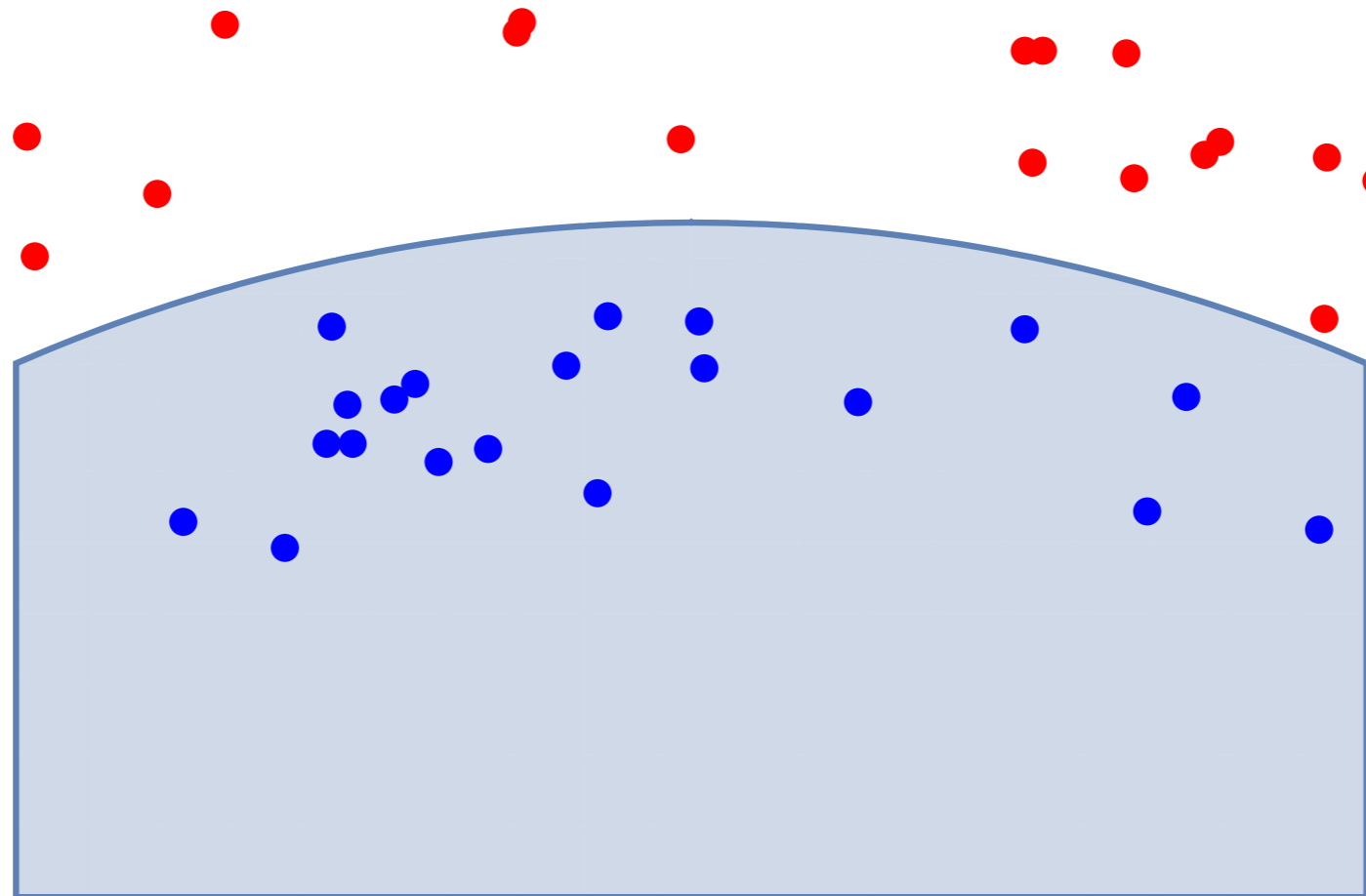
more data, *noise*, labels, priors/regularization/smoothness assumption, ...

complexity & learning: sample size vs. hypothesis space

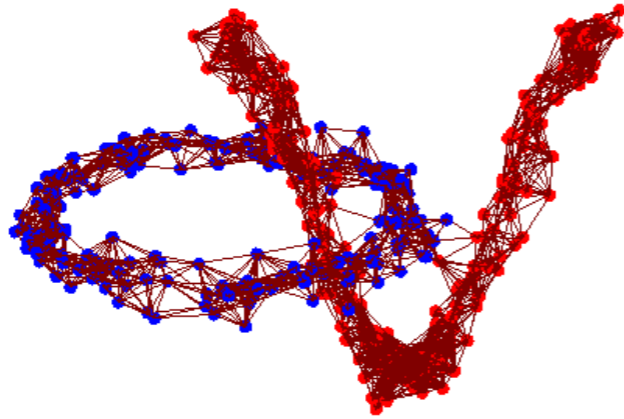
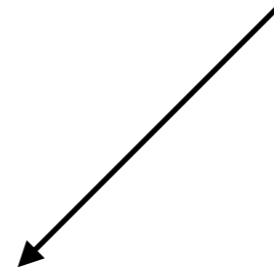
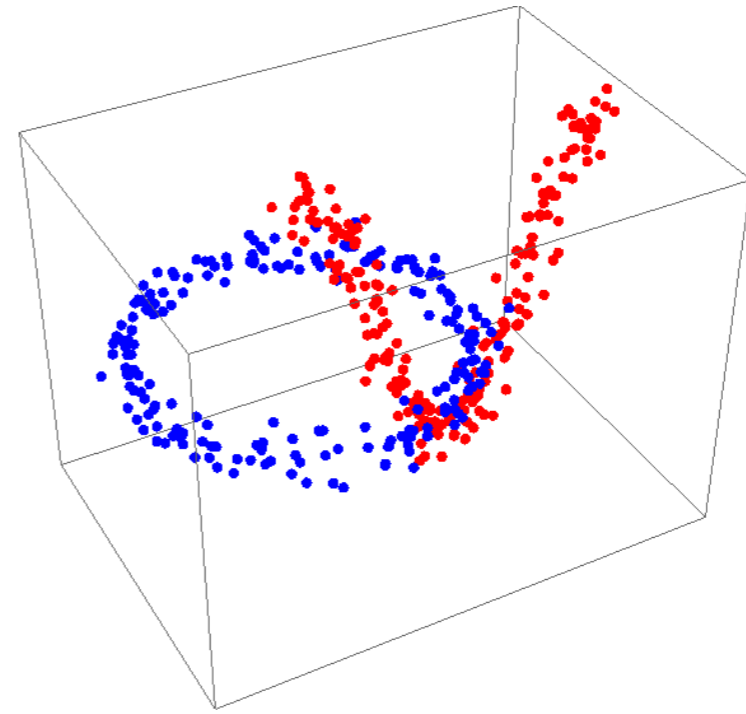
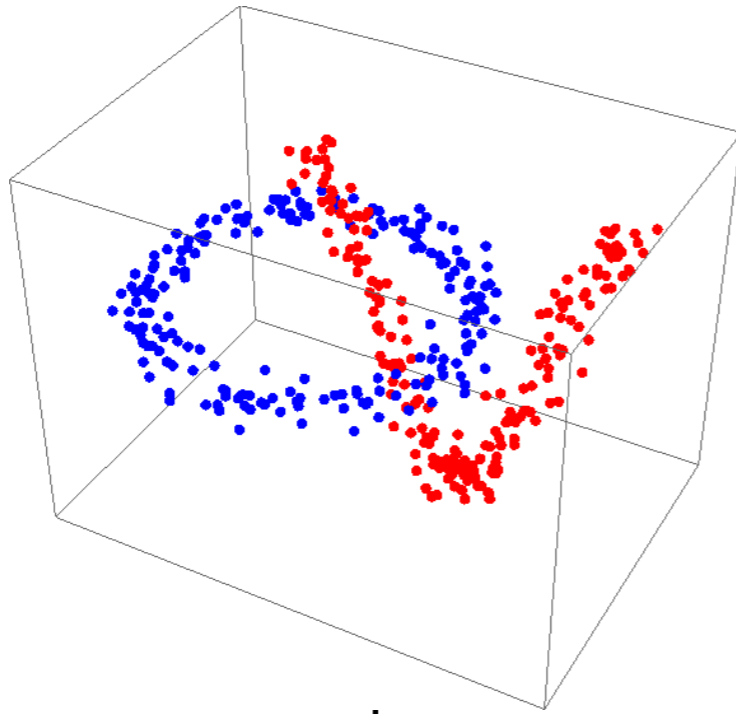
online learning

....

manifold  
assumption



# Metric Embedding (II)



2D !

## Metric Embedding (II)

data “generating” compact *manifold*  $\mathcal{M}$

data: labeled, unlabeled

labels

unsupervised learning

$$X = (X_l, X_u) \subset \mathcal{M}$$

$$(Y, X_l)$$

$$X = X_u, \quad Y = \emptyset$$



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Hilbert space embedding

$$\mathcal{H}_K \ni f: X \rightarrow \mathbb{R}$$

Mercer kernel  $K: X \times X \rightarrow \mathbb{R}$



RKHS



$(\mathcal{H}_K, \|\cdot\|_K)$

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RKHS



$(\mathcal{H}_K, \|\cdot\|_K)$

$$\forall f \in \mathcal{H}_K: \langle h_x, f \rangle_K = f(x)$$

$$K(x, x') = \langle h_x, h_{x'} \rangle_K$$

$$\langle K(x, \cdot), f \rangle_K = f(x)$$

## Metric Embedding (II)

$$E(f) = \frac{1}{l} \sum_{i \in [l]} L(x_i, y_i, f) + \lambda_A \|f\|_K^2 + \lambda_I \int_{\mathcal{M}} \|\nabla_{\mathcal{M}} f\|^2 d\mu_X$$

embedding  
quality

labels, loss:  
supervision

control:  
hypothesis space

intrinsic  
geometry

**key problem:** how do labels (symbols) emerge from raw data?

## Metric Embedding (III)

**Euclidean** case  $D_{ij} = (d(x_i, x_j))^2$

$$\Leftrightarrow -\frac{1}{2}CDC \geq 0, \quad C = I - \frac{1}{|X|}ee^\top$$

 embedding, approximation etc. by *semidefinite programming*

# Metric Embedding (III)

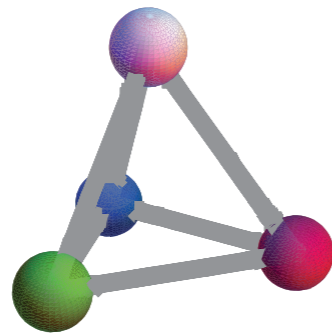
Euclidean case  $D_{ij} = (d(x_i, x_j))^2$

$$\Leftrightarrow -\frac{1}{2}CDC \geq 0, \quad C = I - \frac{1}{|X|}ee^T$$

➔ embedding, approximation etc. by *semidefinite programming*

Example: Euclidean representation of label metrics

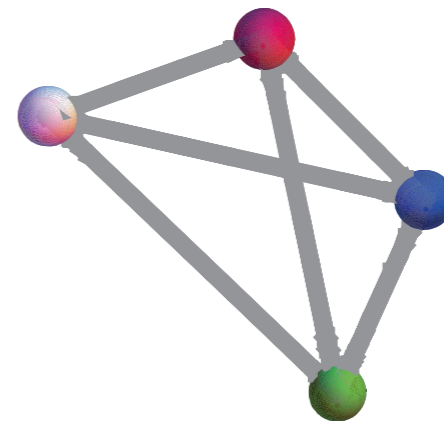
( $\leftrightarrow$  convex relaxation of variational approaches)



Potts



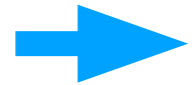
linear



approx.: linear-truncated

# Summing Up

data analysis: 20min brainstorming



- metric geometry
- geometric functional analysis
- differential geometry
- functional analysis, PDEs
- convex analysis

Yet, our understanding is quite limited  
including tools (deep networks) claimed to perform well

→ TDA *may* help!

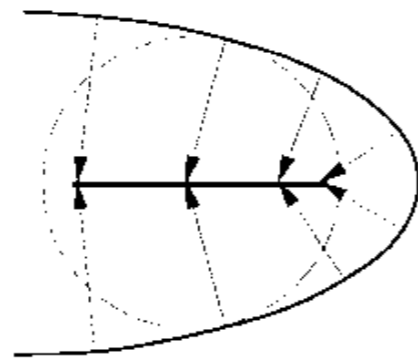
## Remark on TDA

TDA has a long history in computer vision and elsewhere

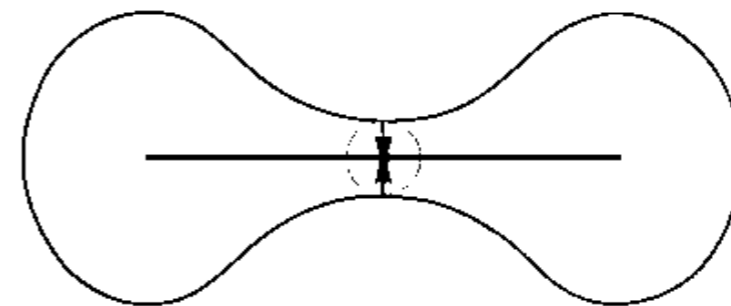
*Blum'67*: “grassfire transform”

distance & medial axis transform, curvature-driven shape evolution, shock graphs, ...

*(Siddiqi et al. IJCV'99)*



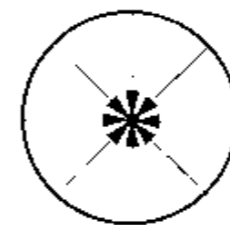
First-Order



Second-Order



Third-Order



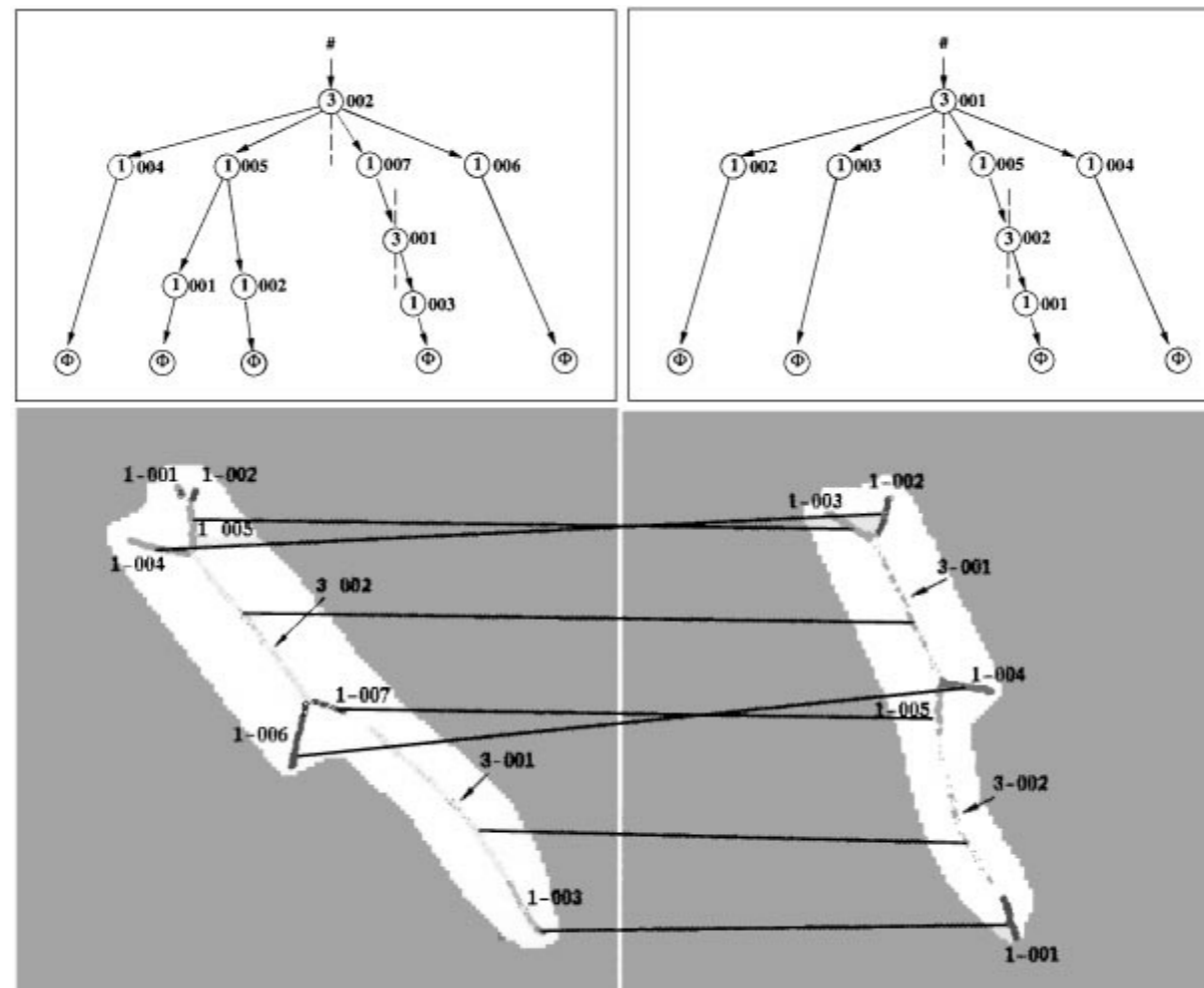
Fourth-Order

# Remark on TDA

*Blum'67*: “grassfire transform”

distance & medial axis transform, curvature-driven shape evolution, shock graphs, ...

maximal subgraph isomorphisms, shock trees & shape matching, etc.

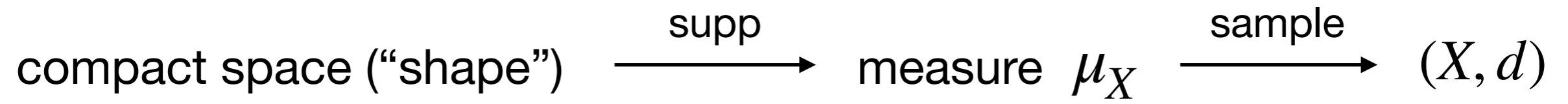


*(Siddiqi et al. IJCV'99)*

**Main objection:** *lack of stability !*



## Remark on TDA



## Remark on TDA

compact space (“shape”)  $\xrightarrow{\text{supp}}$  measure  $\mu_X$   $\xrightarrow{\text{sample}}$   $(X, d)$

**robust** distance to measure (Boissonnat et al. 2018)

$$d_{\mu, m_0}^2(x) = \frac{1}{m_0} \int_0^{m_0} \delta_{\mu, m}^2 dm, \quad m_0 \in (0, 1)$$

$$\delta_{\mu, m}(x) = \inf \{ r > 0 : \mu(\bar{B}_r(x)) > m \}$$

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in terms of the *empirical* measure  $\hat{\mu}_X = \frac{1}{|X|} \sum_{x_i \in X} \delta_{x_i}$

$$d_{\mu, m_0}^2(x) = \frac{1}{k_0} \sum_{x_i \in k_0 \text{NN}_X(x)} \|x_i - x\|^2, \quad m_0 = \frac{k_0}{n}$$

**embedding matters !**

## Remark on TDA

**Consequently:** embedding into the space of (prob.) measures !

$$d_{\mu, m_0}(x) = \min \left\{ \frac{1}{\sqrt{m_0}} W_2(m_0 \delta_x, \nu) : \nu \in \text{Sub}_{m_0}(\mu) \right\}$$

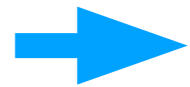
$W_2$  metric !

## Remark on TDA

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$W_2$  metric !



- metric geometry
- geometric functional analysis
- differential geometry
- functional analysis, PDEs
- convex analysis
- optimal transport
- dynamical systems
- PDEs (W-geometry)
- information geometry

## Remark on TDA

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$W_2$  metric !

$$\begin{array}{c} \updownarrow \\ \mu_{x, m_0} = \nu^* \end{array}$$

$$d_{\mu, m_0}(x) = \left( \frac{1}{m_0} \int \|x - h\|^2 d\mu_{x, m_0}(h) \right)^{1/2}$$

### stability

$$d_H(\text{Sub}_{m_0}(\nu), \text{Sub}_{m_0}(\nu')) \leq W_2(\nu, \nu') \quad \implies \quad \text{stability of } d_{\mu, m_0}$$

$$\longleftrightarrow \quad \text{fundamental task, mm-spaces, } d_{GH} \leftarrow d_{GW}$$

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## Hausdorff distance

$$d_H^X(A, B) = \max \left\{ \sup_{a \in A} \inf_{b \in B} d(a, b), \sup_{b \in B} \inf_{a \in A} d(a, b) \right\} \quad A, B: \text{ shapes}$$

$$= \inf_R \sup_{(a,b) \in R} d(a, b) \quad R \subset A \times B \text{ correspondences}$$

## Gromov-Hausdorff distance

$$d_{GH}(X, Y) = \inf_{Z, f, g} d_H^Z(f(X), g(Y)) \quad f, g: \text{ isometries}$$

$$= \frac{1}{2} \inf_R \sup_{\substack{(x, y) \in R \\ (x', y') \in R}} \left| d_X(x, x') - d_Y(y, y') \right|$$

## Gromov-Wasserstein distance

$$d_{GW,p}(X, Y) = \frac{1}{2} \inf_{\mu} \left( \iint \left| d_X(x, x') - d_Y(y, y') \right|^p d\mu(x, y) d\mu(x', y') \right)^{1/p}$$

$\mu$  couples  $\mu_X, \mu_Y$