# Coxeter groups with (FA)

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#### Abstract

Recall that a group has property (FA) when for any action (without inversion) on a tree there is a global fixed point. Last time we have discussed some criteria for a group to be (FA); in particular, if the group is denumerable, it cannot be an amalgam. Today we look at groups with a *presentation*.

**Definition.** Let S be a set,  $\mathcal{F}(S)$  the free group over S, and  $R = (r_j)_{j \in J}$  a family of words in  $\mathcal{F}(S)$ . A presentation is then defined by  $\langle S | R \rangle := \mathcal{F}(S) / \langle \langle R \rangle \rangle$ , where  $\langle \langle R \rangle \rangle$  is the smallest normal subgroup containing R.

It is known that every group G is isomorphic to a group  $\langle S \mid R \rangle$ . Our goal for today is to derive from a group's presentation if it has property (FA). In particular, we will show that every 2-spherical Coxeter group – sometimes referred to as abstract reflection group – has property (FA). To achieve this, we first look at automorphisms of a tree and their fixed points.

# References

[Serre] J. Serre. Trees, 1977.

[Thomas] A. Thomas. Geometric and Topological Aspects of Coxeter Groups and Buildings, 2018.

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# 1 Fixed points of an automorphism of a tree

We formulate some needed terms for the study of automorphisms.

#### 1.1 Distance and subtrees

Recall that a **geodesic** is a path c without backtracking. We know that if X is a tree, its geodesics are *unique* and *injective*.

Let P - Q denote the geodesic joining two vertices P and Q of a tree, where P and Q lie in subtrees  $T_1$  resp.  $T_2$ .



Figure 1: A tree X with subtrees  $T_1, T_2$ 

Definition. The distance between two subgraphs is defined as

$$\operatorname{dist}(T_1, T_2) = \inf_{P \in T_1, Q \in T_2} \ell(P, q)$$

where  $\ell$  is the length of the geodesic joining P and Q.

*Remark.* If there is no path (that is,  $T_1$  and  $T_2$  lie in different connected components), we set the distance to  $\infty$ . Since trees are connected, this case does not apply to us. If the distance is 0,  $T_1$  and  $T_2$  meet at some vertex.

If X is a tree, we can make the following statements about distance.

**Lemma 1.** Let  $T_1$  and  $T_2$  be disjoint subtrees of a tree X, with  $dist(T_1, T_2) = n$ .

1. There is a unique pair  $(P_1, P_n)$  in  $vert(T_1) \times vert(T_2)$  such that

$$\ell(P_1, P_n) = n.$$

2. If  $Q_1 \in vert(T_1)$  and  $Q_2 \in vert(T_2)$ , then

$$\ell(Q_1, Q_2) = \ell(Q_1, P_1) + n + \ell(P_n, Q_2).$$
(1)

3. Every subtree T of X with  $T \cap T_1 \neq \emptyset$  and  $T \cap T_2 \neq \emptyset$  contains the geodesic  $P_1 - P_n$  (with  $P_1$ ,  $P_n$  as in 1.)

We say that  $P_1 - P_n$  is the geodesic **joining**  $T_1$  and  $T_2$ .



Figure 2: Juxtaposing of geodesics

*Proof.* Let  $P_1 \in \operatorname{vert}(T_1)$  and  $P_n \in \operatorname{vert}(T_2)$  such that  $\ell(P_1, P_n) = n$ . (Such a pair exists by definition, but it is not unique a-priori.) We first prove the formula (1).

2. Consider the (unique) geodesic  $P_1 - P_n$  in X. The inner vertices  $P_2, \ldots, P_{n-1}$  do not belong to either  $T_1$  or  $T_2$ ; otherwise, the geodesic would not have minimal length.

Let now  $Q_1 \in T_1$ ,  $Q_2 \in T_2$  with geodesics  $Q_1 - P_1$  resp.  $Q_2 - P_n$ . By the above, the juxtaposed path

$$Q_1 - Q_2 \coloneqq (Q_1 - P_1, P_1 - P_n, P_n - Q_2)$$

is without backtracking, which implies (1).

1. Let  $(Q_1, Q_2)$  be a pair of vertices such that  $\ell(Q_1, Q_2) = n$ . By (1),

$$\ell(Q_1, P_1) = \ell(P_n, Q_2) = 0,$$

that is,  $Q_1 = P_1$  resp.  $P_2 = Q_2$ .

3. Let T be a subtree meeting both  $T_1$  and  $T_2$ . Let  $Q_1 \in T_1$  and  $Q_2 \in T_2$ , and let  $\gamma := Q_1 - Q_2$  be the unique geodesic joining  $Q_1$  and  $Q_2$  in X; by 2. this geodesic contains  $P_1 - P_n$ .

Let  $\gamma_T$  be the geodesic joining  $Q_1$  and  $Q_2$  in the subtree T. As X contains no circuits, the paths  $\gamma$  and  $\gamma_T$  must coincide, and the claim follows.

### 1.2 Automorphisms with fixed points

Last time, we have formulated fixed points for an action  $G \curvearrowright \operatorname{Mor}(X)$ . In this auxiliary section, it suffices to look at general automorphisms in X, without necessary involvement of a group action.



Figure 3: A tree X may contain no circuits

**Definition.** Let s be an automorphism without inversion of a tree X, that is  $sy \neq \overline{y}$  for all  $y \in \text{edge}(X)$ . We say that s has a **fixed point** if the subgraph  $X^s \subset X$  of points fixed by s is non-empty, in which case it is a tree. [As before for  $X^G$ , if s fixes two points in a tree, it must fix the geodesic joining them, implying connectivity.]

If an automorphism s has *some* fixed point, the following proposition will allow us to construct a fixed point, by considering the geodesic joining any point P in the tree with its image under s.

**Proposition 2.** Let s be an automorphism without inversion of a tree X. Suppose s has a fixed point. Let  $P \in vert(X)$ , and let  $dist(P, X^s) = n$ . Let P - P' be the geodesic joining P to  $X^s$ . (see Lemma 1.)

Then the geodesic P - sP is obtained by juxtaposing the geodesics P - P'and P' - sP = s(P' - P).

*Remark.* The last equality P' - sP = s(P' - P) holds by definition of a graph morphism.



Figure 4: The geodesic P - sP

*Proof.* If  $P \in X^s$ , then sP = P and the statement is clear. Let therefore  $P \notin X^s$ , that is,  $dist(P, X^s) \ge 1$ .

Let  $y \notin X^s$  denote the edge of the geodesic P - P' with origin  $P' \in X^s$ . There holds  $sy \neq y$ ; otherwise,  $y \in X^s$ . It follows that the path obtained by juxtaposing P' - sP and P - P' is without backtracking; by uniqueness, this path is the geodesic s - sP.

Corollary.  $\ell(P, sP) = 2n$ .

Proof. By Proposition 2, 
$$\ell(P, sP) = \ell(P - P') + \underbrace{\ell(P' - sP)}_{=n \ (s \ \text{aut.})}$$

**Corollary.** The midpoint of P - sP is fixed by s.

*Proof.* By Proposition 2, the midpoint of P - sP is given by  $P' \in X^s$ .

## 2 Groups with fixed points

We now have all required tools to derive property (FA) from a group presentation. We formulate our main result:

**Proposition 3.** Consider the group  $G = \langle a_i, b_j \rangle$  with subgroups  $A = \langle (a_i)_{i \in I} \rangle$ ,  $B = \langle (b_j)_{j \in J} \rangle$ . Assume that G acts on a tree X so that  $X^A \neq \emptyset$ ,  $X^B \neq \emptyset$ , and so that for all pairs (i, j) the automorphism has  $a_i b_j$  has a fixed point. Then  $X^G \neq \emptyset$ , that is, G has a fixed point.



Figure 5:

*Proof.* By definition,  $X^G = X^A \cap X^B$ . Assume that  $X^A$  and  $X^B$  are disjoint, and let P - Q denote the geodesic joining them, with  $P \in X^A$ ,  $Q \in X^B$ . (cf. Lemma 1).

Let  $P_1$  be the vertex of P - Q at distance 1 from P. We have  $P_1 \notin X^A$ ; it follows there is an index *i* such that  $a_i P_1 \neq P_1$ . The path obtained by juxtaposing is therefore without backtracking; it is the geodesic  $Q - a_i Q$  with midpoint P.

As  $Q \in X^B$ , we have  $b_j Q = Q$  for all j, in particular  $a_i Q = a_i b_j Q$ . Since  $a_i b_j$  has a fixed point (by assumption), Proposition 2 shows that the midpoint  $P \in X^A$  of  $Q - a_i b_j Q$  is fixed by  $a_i b_j$ , that is  $a_i b_j P = P$  resp.  $b_j P = a_i^{-1} P = P$ . This shows that P is fixed by all  $b_j$ ; a contradiction.

We have the following simple consequence:

**Corollary.** Let a, b and c be three automorphisms of a tree such that abc = 1. If a, b, c have fixed points, then they have a common fixed point.

*Proof.* Let  $P \in X^c$ . Then  $ab \underbrace{cP}_{=P} = P = abP$  by assumption; it follows that ab has a fixed point. By Proposition 3, a, b, ab have a common fixed point Q. As abcQ = Q = abQ, this point is also fixed by c.

Proposition 2 is somewhat unwieldy when considering group presentations  $\langle S \mid R \rangle$ . We therefore formulate:

**Corollary.** Suppose that  $G = \langle s_1, \ldots, s_n \rangle$  is a finitely generated group, and that  $s_j$  and  $s_i s_j$  have fixed pionts for all  $i, j \in \{1, \ldots, m\}$ ,  $i \neq j$ . Then G has a fixed point.

*Proof.* Proceed by induction on m, applying Proposition 2.

## 3 Coxeter groups

**Definition.** Let I be a **finite** index set. A **Coxeter group** is a group W with presentation

$$W \cong \langle S \mid s_i^2 = 1 \ \forall i \in I, \ (s_i s_j)^{m_{ij}} = 1 \ \forall i \neq j \rangle$$

where  $m_{ij} \in \{2, 3, 4, ...\} \cup \{\infty\}$  and  $m_{ij} = m_{ji}$  for all  $i, j \in I$ . S is called the **Coxeter generating set**.  $m_{ij} = \infty$  denotes that  $s_i s_j$  is of infinite order.

*Remark.* It is a priori not clear what the order of elements  $s_i s_j$ ,  $m_{ij} \neq \infty$  is; all we know that the order divides  $m_{ij}$ . We may prove that the presentation is "honest" using a faithful linear representation

$$\rho: W \to GL_n(\mathbb{R}),$$

the **Tits representation** (by Jacques Tits).

**Example.** The dihedral groups  $D_{2m}$  (isometry groups of a regular polygon) give a simple class of examples for Coxeter groups. For m = 3, we have the representation:

$$D_6 = \langle s_1, s_2 \mid s_1^2 = s_2^2 = (s_1 s_2)^3 = 1 \rangle$$



Figure 6: Presentations of the dihedral group  $D_6$ .

By replacing an axis of reflection with an axis of rotation, we get:

$$G = \langle r, s \mid r^m = s^2 = 1, \ rs = sr^{-1} \rangle$$

While the group G is isomorphic to  $D_6$ , it is no longer a Coxeter group by the definition above.

*Remark.* More generally, different Coxeter generating sets may generate the same group W (up to isomorphism). For example,  $D_{12}$  has the presentations:

$$W = \left\langle s_1, s_2 \mid s_1^2 = s_2^2 = (s_1 s_2)^6 = 1 \right\rangle,$$
  
=  $\left\langle t_1, t_2, t_3 \mid t_1^2 = t_2^2 = (t_1 t_2)^3 = (t_2 t_3)^2 = (t_3 t_1)^2 = 1 \right\rangle.$ 

**Definition.** A Coxeter group (W, S) is **2-spherical** if  $m_{ij} \neq \infty$  for each (i, j).

We now formulate our final proposition.

**Proposition 4.** Let (W, S) be a 2-spherical Coxeter group. Then W has property (FA).

*Proof.* By definition, each generator and pair  $s_i s_j$  are of finite order, and thus have a fixed point when acting on a tree. By Proposition 3, W has property (FA).