

Hyperbolic Manifolds - Lecture 7

Note Title

24/11/2020

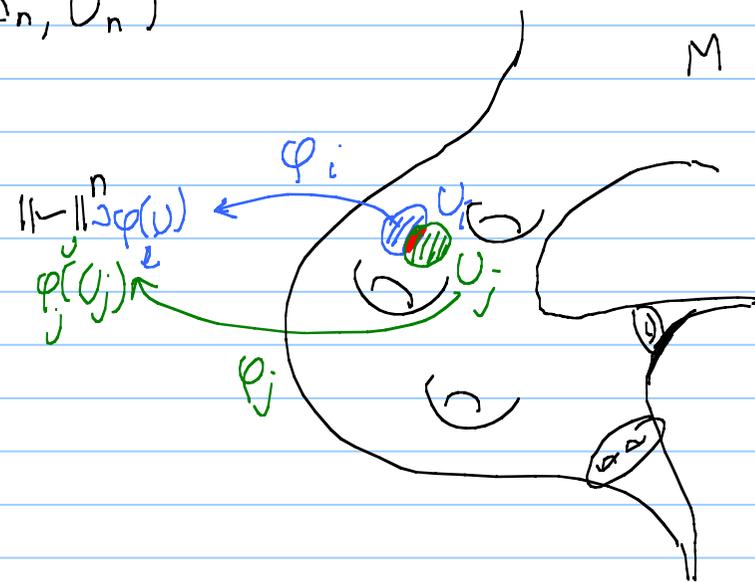
Hyperbolic surfaces

Def 1: A (complete) hyperbolic n -mfd is a (complete) Riemannian n -mfd (M, g) locally isometric to $\mathbb{H}^n (= \mathbb{I}^n, \Delta_n, \mathcal{U}_n)$

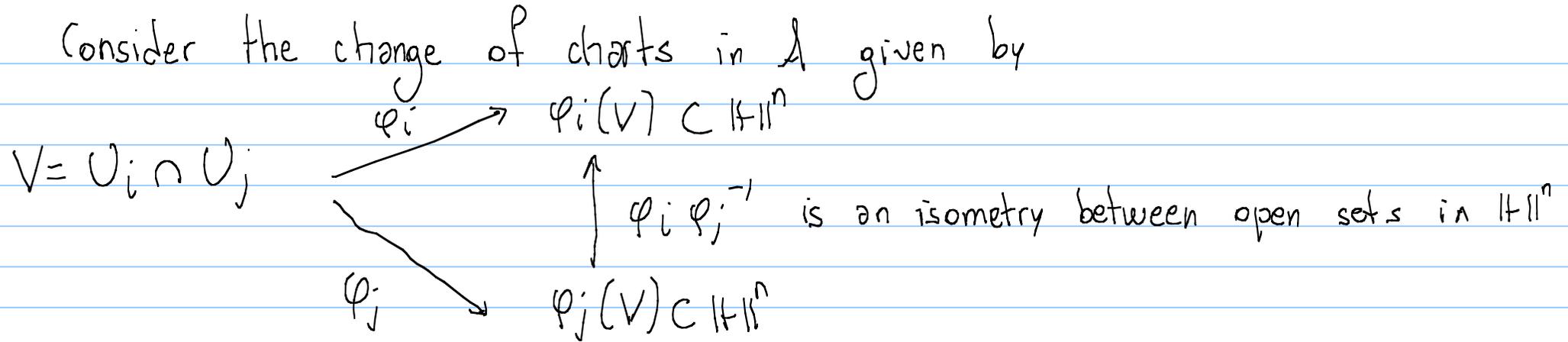
i.e. there exists an atlas

$$\mathcal{A} = \left\{ \varphi_j: \mathcal{U}_j \longrightarrow \mathbb{H}^n \right\}_{j \in \mathcal{J}}$$

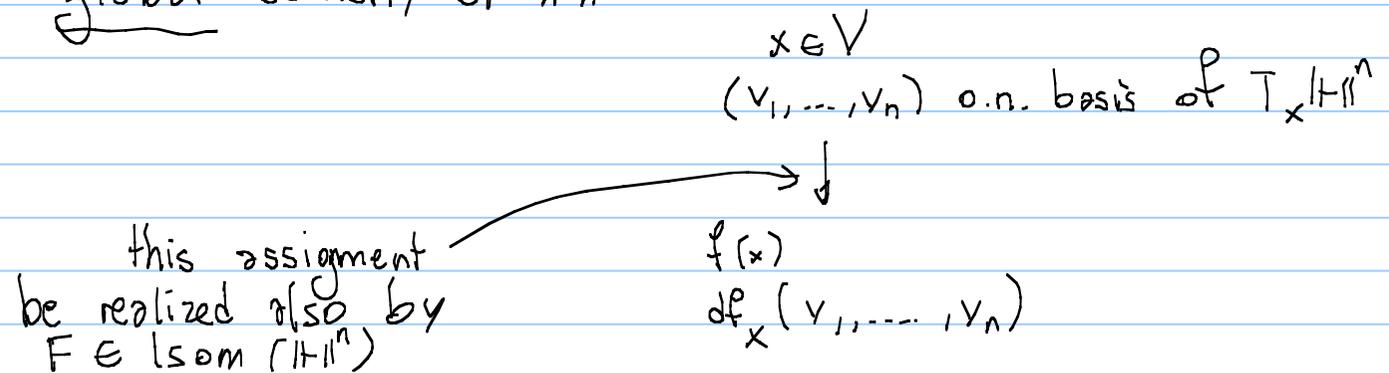
where each φ_j is an isometry between $(\mathcal{U}_j, g) \longrightarrow (\varphi(\mathcal{U}_j), g_{\mathbb{H}^n})$



Consider the change of charts in A given by



Obs: Any isometry $f: V \rightarrow V'$ between open sets in \mathbb{R}^n is the restriction of a global isometry of \mathbb{R}^n



but, since isom. are determined by the first order, we have $f = F|_{V_n}$ \curvearrowright connected

Thus Def 1 is equiv to

Def 2 A (complete) hyperbolic n-mfd is a n-mfd M together with an atlas

$$\mathcal{A} = \{ \varphi_j : U_j \longrightarrow \varphi_j(U_j) \subset \mathbb{H}^n \}$$

s.t. the change of charts $\varphi_i \circ \varphi_j^{-1}$ are restrictions

of global isometries of \mathbb{H}^n . Denote by g the Riemannian metric on M defined locally by $\varphi_j^* g_{\mathbb{H}^n}$.

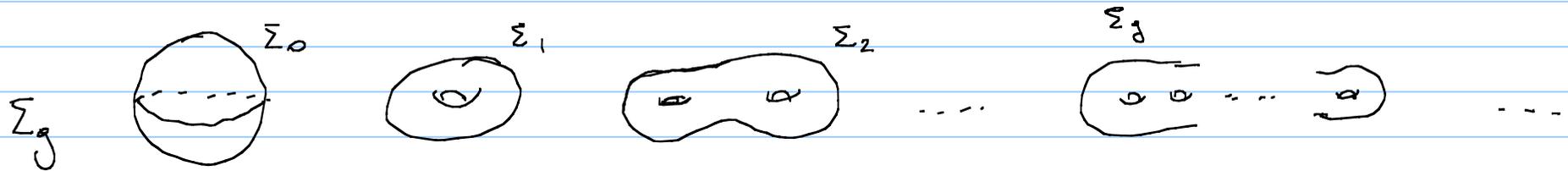
ex. check that this does not depend on the choice of local charts

The hyp. mfd M is complete if (M, g) is complete.

Now we want to construct hyp 2-mfd's, that is hyp. surfaces

Recall

Thm (Classification of surface): Any closed ^{cpt. + no boundary} connected orientable 2-mfd Σ is diffeomorphic to one of the following standard ones (called Σ_g)



$g=0$
 $\chi=2$

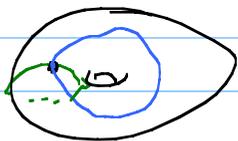
$g=1$
 $\chi=0$

$g=2$
 $\chi=-2$

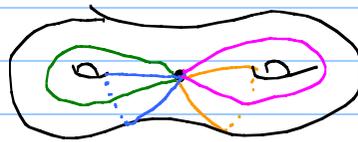
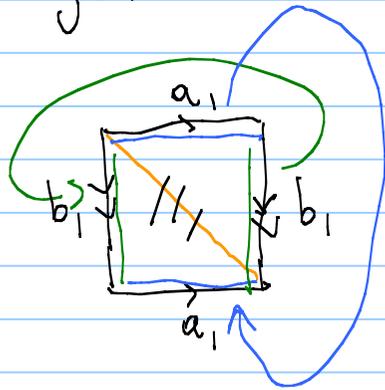
$\chi=2-2g$ \leftarrow genus of the surface
(complete topological invariant)

$\chi = 2 - 2g$
||
Euler characteristic \leftarrow can be easily computed from a triangulation]

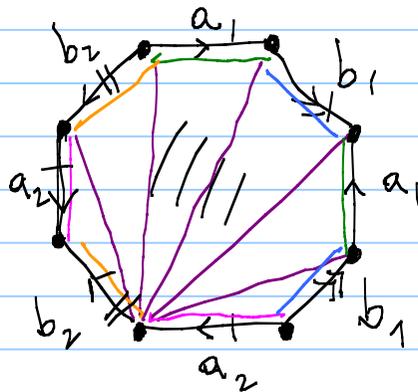
Equivalently we can present $\Sigma_{g \geq 1}$ as a quotient of a $4g$ -gon with identifications of the sides



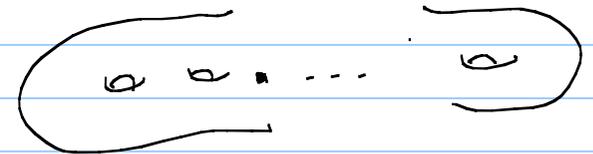
$g=1$



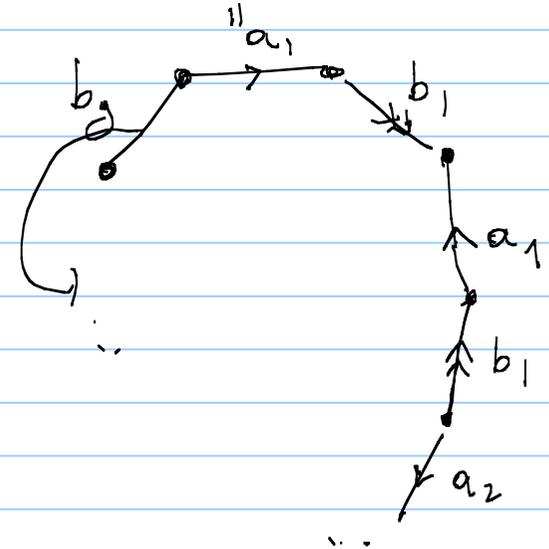
$g=2$



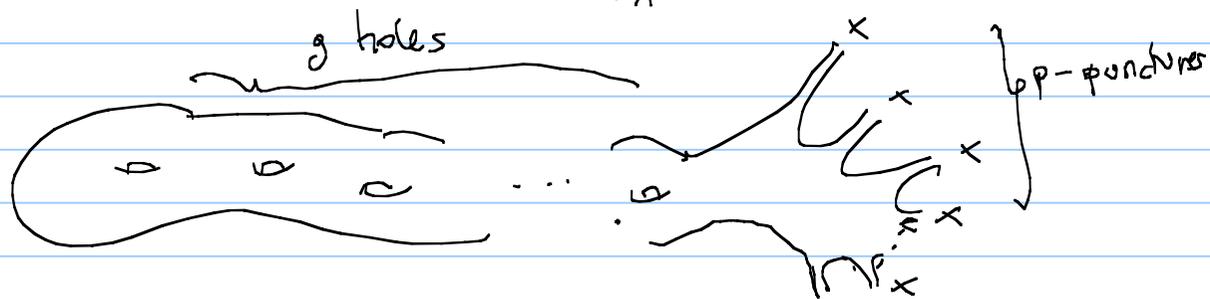
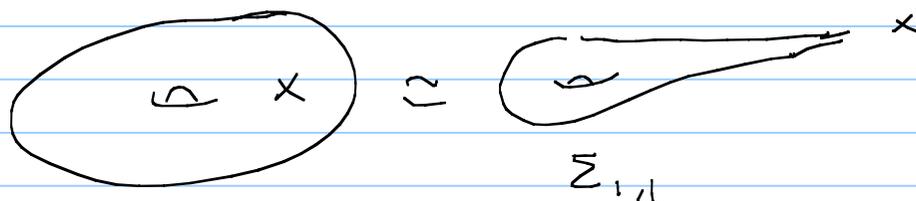
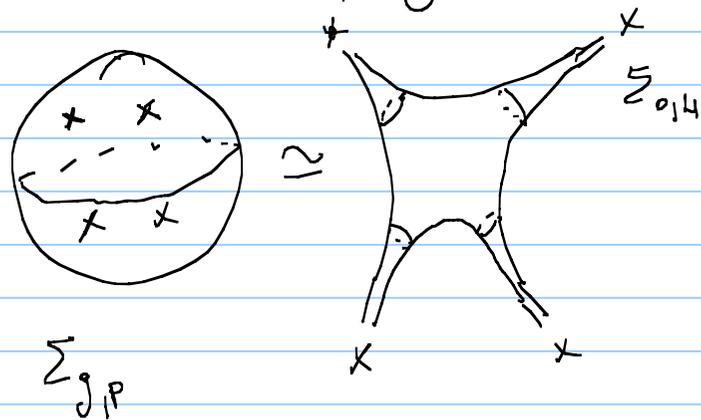
...



Σ_g



The surfaces we are going to work with have also punctures, that is they are obtained from a closed surface by removing a finite collection of points. The pair (genus, number of punctures) = (g, p) is a complete topological invariant of a surface with punctures.



In general $\Sigma_{g,p} =$

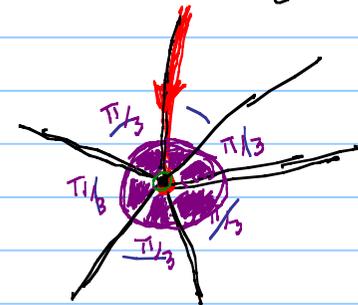
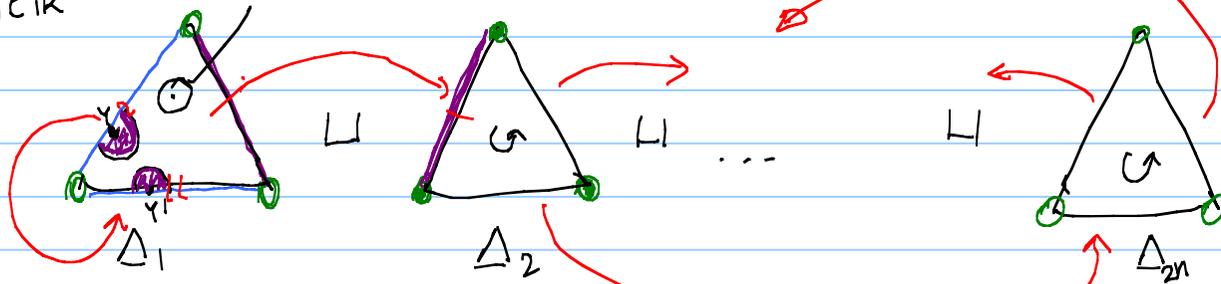
Ideal triangulations

A way to construct surfaces with punctures is the following:

- ① Start with $2n$ Euclidean ~~simplices~~ (equilateral triangles with side length = 1)

two half disks
glue to a honest disk in \mathbb{R}^2
 $\mathbb{C}P^1 \cong \mathbb{R}P^2$

isom. to a ball in \mathbb{R}^3
Ideal hyp-triangles



2π
 π
 $\pi/3 \cdot \text{nb of sectors}$

- ② glue their sides in pairs with isom. (orientation reversing)
(After step 2 we get a closed orientable surface Σ , not necessarily connected)
- ③ ~~remove the vertices from $\Sigma = \text{quotient}$~~

ex. check that this is 2π around every pt.

The resulting object is a surface with punctures

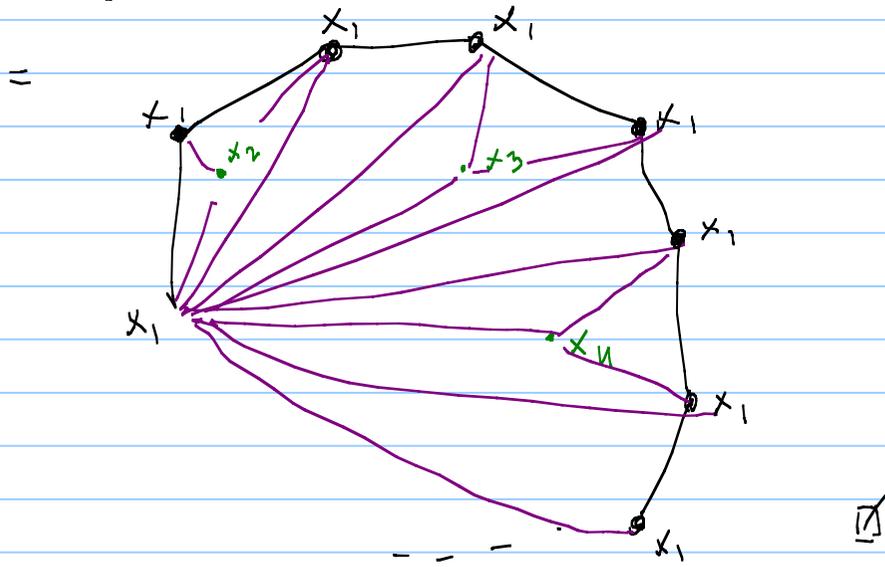
If we assume that $\Sigma = \text{quotient}$ is connected, then $\Sigma = \Sigma_g$
and we can compute the genus by

$$\begin{aligned} 2 - 2g = \chi &= \# \text{ nb of triangles } T = 2n \\ &\quad - \# \text{ nb of edges } E = 3T/2 = 3n \\ &\quad + \# \text{ nb of vertices } V = p \\ &= V - n \quad \Rightarrow \quad g = \frac{n+2-V}{2} \quad p = V \end{aligned}$$

$$\Sigma - \text{vertices} = \sum_{j,p} = \sum \frac{n+2-V}{2} \quad , \quad \nu$$

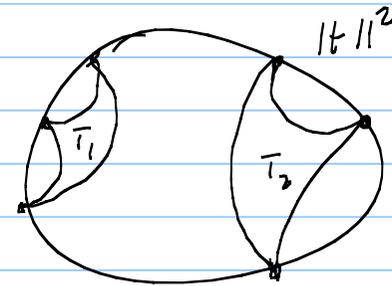
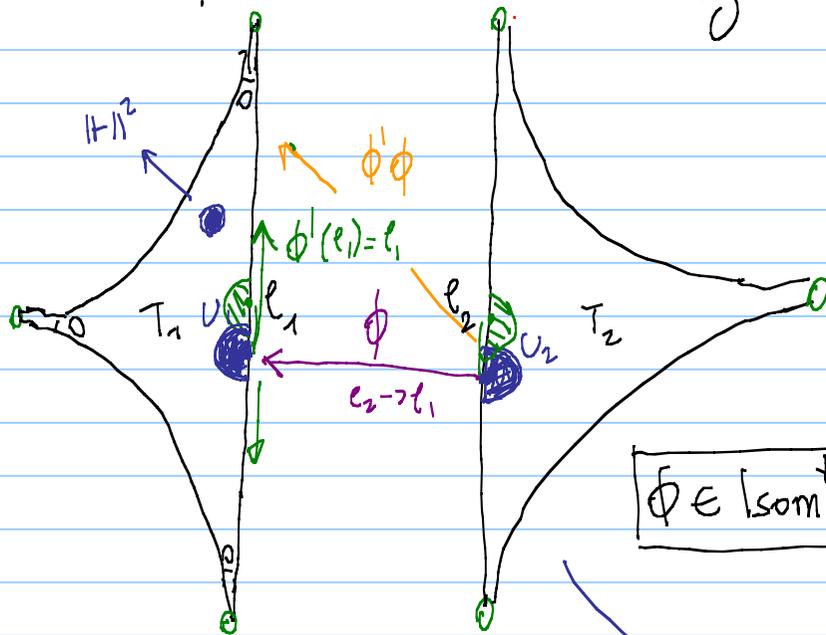
Proposition: Every surface with punctures has an ideal triangulation

Pf. $\Sigma_{g,p} = \Sigma_g - \{x_1, \dots, x_p\}$



Geometric ideal triangulations

We can replace Euclidean triangles Δ_i with ideal hyperbolic triangles T_i

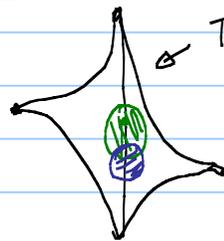


There are many isometries that carry l_2 to l_1

$$\phi(l_2) = l_1$$

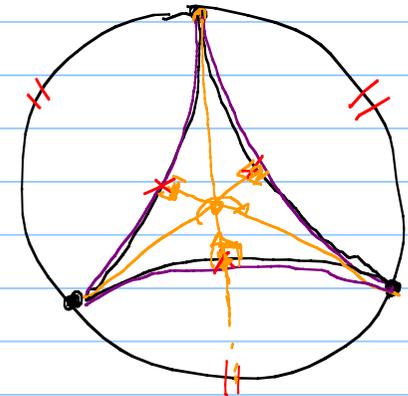
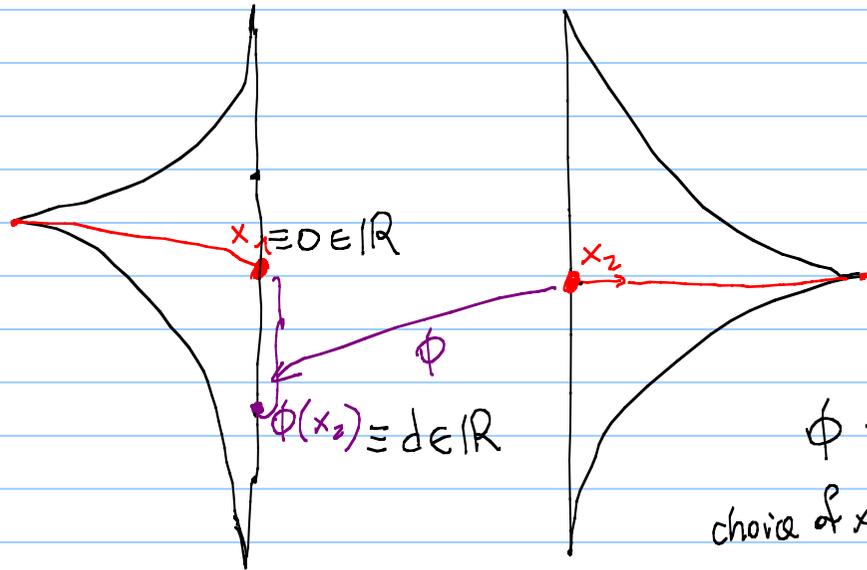
$T_1 \cup \phi(T_2) \subset \mathbb{H}^2$ is a quadrilateral

$$U_1 \cup U_2 \rightarrow \mathbb{H}^2$$



$$\mathbb{R} \rightarrow \mathbb{R}$$

Need: For every pair of edges that must be identified we need an isometry that identifies them



$\phi: \mathbb{R} \rightarrow \mathbb{R}$
 choice of $x_2 \rightarrow \parallel \parallel$ choice of x_1
 $x \rightarrow x + d$ uniquely determines $\phi!$

\Rightarrow For every edge pair we need a real number d that says where the basepoint of one side is mapped (by the isometry) on the other side

In conclusion we have

$$\underbrace{\mathbb{C} \subseteq \mathbb{R}}_{E = \# \text{ edge pairs}}$$

Proposition: For every choice of parameters $\{d(e)\}_{e \in \text{edge pairs}}$ the metrics on the triangles T_i define a Riem. metric on $\bigsqcup T_i$ / isometri pairings determined by $\{d(e)\}_{e \in \text{edge pairs}}$

which is locally isometric to \mathbb{R}^2 .