

Aubry & Mañé Sets

M compact, $L: TM \rightarrow \mathbb{R}$ Tonelli Lag.

All curves in M abs. cont.

① Recap

• $\gamma: \mathbb{R} \rightarrow M$ is glob. min for L if

$$\forall \alpha, \beta: d_L(\gamma|_{[\alpha, \beta]}) = \min d_L(\sigma)$$

$$\sigma: [\alpha, \beta] \rightarrow M$$

$$\sigma(\alpha) = \gamma(\alpha), \sigma(\beta) = \gamma(\beta).$$

• $\gamma: \mathbb{R} \rightarrow M$ is time-free min. for L if

$$\forall \alpha, \beta: d_L(\gamma|_{[\alpha, \beta]}) = \min_{\sigma: [\alpha', \beta'] \rightarrow M} d_L(\sigma)$$

$$\sigma(\alpha') = \gamma(\alpha), \sigma(\beta') = \gamma(\beta).$$

γ time-free min. \Rightarrow γ global min.

γ global min. for $L \Rightarrow \gamma$ global min. for $L + k$, $k \in \mathbb{R}$.

② Mañé Potential & Crit. Value

$$x, y \in M, T > 0 \quad C_T(x, y) := \left\{ \gamma: (0, T] \rightarrow M \mid \gamma(0) = x, \gamma(T) = y \right\}$$

Def: $\phi_h(x, y, T) := \inf_{y \in C_T(x, y)} d_{L+h}(y)$ this is actually a min

$$\Phi_h(x, y) := \inf_{T > 0} \phi_h(x, y, T) \quad \text{for } h \in \mathbb{R}$$

is this also a min?

(1)

When is $\phi_h(x, y) > -\infty$?

If $\exists T > 0, y \in G(x, x) \quad d_{L+h}(y) < 0$,

then $d_{L+h}(y^n) = n \cdot d_{L+h}(y) \rightarrow -\infty$

$$\Rightarrow \phi_h(x, x) = -\infty$$

Prop: For all $x, y \in M$ have

$$\phi_h(x, y) \begin{cases} = -\infty & \text{if } h < c(L) \\ \in \mathbb{R} & \text{if } h \geq c(L) \end{cases}$$

where $c(L) := \sup \{ h \mid \exists x \in M, T > 0, y \in G(x, x) \text{ with } d_{L+h}(y) < 0 \}$.

(Maaße crit. value)

Moreover, for $h \geq c(L)$ $\phi_h : M \times M \rightarrow \mathbb{R}$ is Lipschitz.

$(x, y) \mapsto \phi_h(x, y) + \phi_h(y, x)$ is a (pseudo-) metric for $h > c(L)$ ($h > c(L)$).

③ Aubry & Mañé sets

Answer to (1) is yes if $h > c(L)$.

(For $x, y \in M$, have $\phi_h(x, y, T) \rightarrow \infty$ if $T \rightarrow \infty$
if $T \rightarrow 0$)

\Rightarrow We can connect any two pts in M
by a time-free min. of energy $h > c(L)$
 ∇ there are no min. for $h < c(L)$.

Q: What happen at $h = c(L)$?

Df: $\gamma : \mathbb{R} \rightarrow M$ is semi-static for L if

$$\forall a < b : \underset{L+c(L)}{\text{ct}}(\gamma|_{[a,b]}) = \phi_{c(L)}(\gamma(a), \gamma(b)).$$

(i.e. γ time-free min. for $L+c(L)$).

- The Mañé set is

$$\tilde{\mathcal{W}} := \{(x, v) \in TH \mid \exists \gamma \text{ semi-static, } t \in \mathbb{R} \\ \text{s.t. } x = \gamma(t), v = \dot{\gamma}(t)\}$$

Note : - $\tilde{\mathcal{W}}$ is invariant under the EL-flow
 - $\tilde{\mathcal{W}}$ is closed

$$\text{Recall: } \phi_{c(L)}(\gamma(a), \gamma(b)) + \phi_{c(L)}(\gamma(b), \gamma(a))$$

$$(\text{Hence } d_{L+L}(\gamma^{-1}) = -d_{L+L}(\gamma))$$

$$\Rightarrow \phi_L(x, y) \geq -\phi_L(y, x) \quad (\text{for } L \geq c(c))$$

Def: • $\gamma: \mathbb{R} \rightarrow M$ is static for L if

$$\text{facts: } d_{L+c(c)}(\gamma|_{[a, b]}) = -\phi_{c(c)}(\gamma(b), \gamma(a))$$

$$(\text{i.e. } \gamma \text{ is semi-static and} \\ \phi_{c(c)}(\gamma(a), \gamma(b)) = -\phi_{c(c)}(\gamma(b), \gamma(a)).)$$

• The Aubry set is

$$\tilde{\mathcal{A}} := \{(x, v) \in TH \mid \exists \gamma \overset{\text{static}}{\not\in} \mathcal{W}, t \in \mathbb{R} : \\ x = \gamma(t), v = \dot{\gamma}(t)\}$$

- Note: - $\tilde{\mathcal{X}}$ is invariant under EL-flow
- $\tilde{\mathcal{X}}$ is closed
 - $\tilde{\mathcal{X}} \subseteq \bar{N}$

④ α - and ω -limits

For $(x, v) \in \bar{T}M$, set

$$\alpha(x, v) := \left\{ (\gamma, \omega) \in \bar{T}M \mid \exists (t_n) \text{ with } t_n \rightarrow \infty \text{ and } \varphi_{t_n}^L(x, v) \rightarrow (\gamma, \omega) \right\}$$

$$\omega(x, v) := \left\{ (\gamma, \omega) \in \bar{T}M \mid \exists (t_n) \text{ with } t_n \rightarrow \infty \text{ and } \varphi_{-t_n}^L(x, v) \rightarrow (\gamma, \omega) \right\}$$

Prop: Let $(x, v) \in \bar{N}$. Then

$$(1) \quad \alpha(x, v) \subseteq \tilde{\mathcal{X}}$$

$$(2) \quad \omega(x, v) \subseteq \tilde{\mathcal{X}}.$$

Cor: $\tilde{\mathcal{X}} \neq \emptyset$ iff $\bar{N} \neq \emptyset$.

Pf of Prop: (only (2))

Let $(\gamma, \omega) \in \omega(x, v)$ with (t_n) s.t. $t_n \rightarrow \infty$ and $\varphi_{-t_n}^L(x, v) \rightarrow (\gamma, \omega)$.

$$\tilde{r}(t) := \phi_t(x, v), \quad \tilde{\gamma}(t) := p_t^L(y, \omega)$$

$$r := \pi \circ \tilde{r}, \quad \eta := \pi \circ \tilde{\gamma}.$$

$(x, v) \in \tilde{\mathcal{N}} \Rightarrow r$ semi-static.

To show: η static.

Enough to check $\forall s > 0$:

$$\partial_{L+c(L)}(\eta|_{[-s, s]}) + \phi_{c(L)}(\eta(s), \eta(-s)) = 0.$$

Denote $\tilde{r}_n(t) := \tilde{r}(t_n + t)$, $\gamma_n := \pi \circ \tilde{r}_n$.

$\tilde{r}_n(0) \rightarrow (y, \omega)$, so uniqueness of EL-sol.

implies $\tilde{r}_n|_{[-s, s]} \rightarrow \tilde{\gamma}|_{[-s, s]}$, some

without ~.

$$\begin{aligned} & \partial_{L+c(L)}(\eta|_{[-s, s]}) + \phi_{c(L)}(\eta(s), \eta(-s)) \\ &= \lim_n \partial_{L+c(L)}(\gamma_n|_{[-s, s]}) + \lim_n \lim_{m \gg 0} \phi_{c(L)}(\gamma_n(s), \\ & \quad \gamma_n(t_n - t_m - s)) \end{aligned}$$

$$\begin{aligned}
&= \lim_n dt_{L+c(L)} (\gamma_n|_{[s,s]}) \\
&\quad + \lim_n \lim_{m \gg 0} dt_{L+c(L)} (\gamma_n|_{[s, t_m - t_n - s]}) \\
&= \lim_n \lim_m dt_{L+c(L)} (\gamma_n|_{[s, t_m - t_n - s]}) \\
&= \lim_n \lim_m \phi_{c(L)} (\gamma_n(-s), \gamma_n(t_m - t_n - s)) \\
&= \lim_n \lim_m \phi_{c(L)} (\gamma_n(-s), \gamma_m(-s)) \\
&= \phi_{c(L)} (\gamma(1-s), \gamma(-s)) = 0. \quad \square
\end{aligned}$$

⑤ Non-wandering points

Def: $\varphi_+ : X \rightarrow X$ flow . $x \in X$ non-wandering
if $\forall U \ni x \text{ nbh. } \forall \epsilon > 0 \ \exists \delta > 0 \text{ s.t. }$
 $\varphi_+(\delta) \cap U \neq \emptyset$.

Write $S(\varphi) := \{x \in X \mid x \text{ non-wandering}\}$
Facts: $\alpha(x), \omega(x) \stackrel{(*)}{\subseteq} S(\varphi) \quad \forall x \in X$

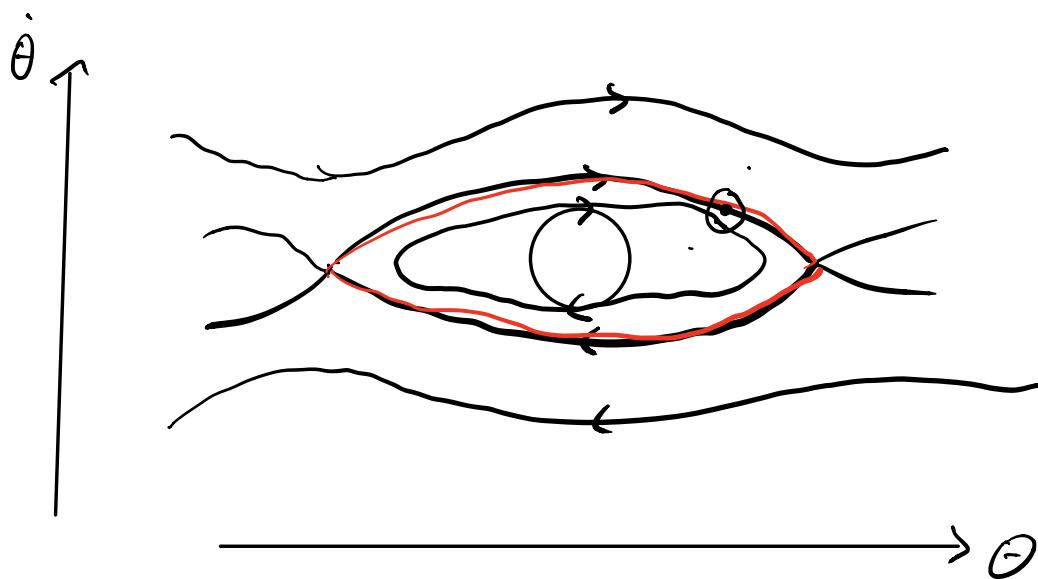
$$\cdot \mathcal{S}(\varphi^L|_{\tilde{N}}) \subseteq \tilde{\mathcal{G}} \quad (\text{need weak } KL\epsilon)$$

Inclusion (*) can be proper:

Consider the pendulum



$$\ddot{\theta} + \sin \theta = 0$$



- : non-wandering pt., which are neither α - nor ω -limits.

⑥ Mañé Lagrangians

Let $X \in \Gamma(TM)$ vector field, $v \geq 2$

Define a Lag. $L_x : TM \rightarrow \mathbb{R}$ $(x, v) \mapsto \frac{1}{2} \|v - X(x)\|^2$

where $\|\cdot\|$ comes from a Riem. metric.

$$\text{Graph}(X) = X(M) = \{(x, v) \in TM \mid v = X(x)\}$$

$$L_x|_{\text{Graph}(X)} = 0, L_x|_{\text{Graph}(X)^c} > 0$$

$$\Rightarrow dL_x(r|_{[a,b]}) \begin{cases} = 0 & \text{if } \dot{r}(t) = X(r(t)) \text{ for} \\ & \text{all } t \\ > 0 & \text{else} \end{cases}$$

\Rightarrow integral curves of X are time-free
min. for L_x .

$$\text{Also: } \text{Graph}(X) \xrightarrow{\phi^*} \text{Graph}(X)$$

$$\pi \downarrow \quad \quad \quad \mathcal{S} \quad \quad \quad \downarrow \pi$$

$$M \xrightarrow{\phi^*} M$$

It turns out that $\text{Graph}(X) \subseteq \tilde{\mathcal{U}}(L_x)$.

This is true because integral curves are
semi-static.