Minimizing properties of geodesics and convex neighborhoods

Seminar Riemannian Geometry Summer Semester 2015 Prof. Dr. Anna Wienhard, Dr. Gye-Seon Lee

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1. Normal spheres

In the sequal, we understand the tangent space to T_PM at $v \in T_pM$ as T_PM itself.

Lemma 1 (Gauss). Let $p \in M$, $v \in T_pM$ s. t. exp_pv is defined. Let $w \in T_vT_pM$. Then $\langle (dexp_p)_v(v), (dexp_p)_v(w) \rangle = \langle v, w \rangle.$

Proof. Recall that

$$(dexp_p)_v(v): T_pM \to T_vexp_pM$$
, whereas, $T_vB_{\varepsilon}(0) \subset T_vT_pM \cong T_PM$.

We shall prove this lemma in three steps.

- (i) $\langle (dexp_p)_v(v), (dexp_p)_v(v) \rangle = \langle v, v \rangle.$
- (ii) $\langle (dexp_p)_v(v), (dexp_p)_v(w_N) \rangle = 0$, where $w = w_T + w_N$.

(iii)
$$\frac{\partial}{\partial t} \langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial s} \rangle = 0.$$

(i) $(dexp_p)_v(v) = v.$

Let u be a curve in T_pM , $u : \mathbb{R} \supset I \rightarrow T_pM$, such that $u(0) := v \in T_vT_pM \cong T_PM$. Choose u(t) = tv among its equivalent classes, namely $\tilde{v}(t) = v(t + \alpha)$, where $\alpha \in \mathbb{R}$. With this construction,

$$\langle (dexp_p)_{v}(v), (dexp_p)_{v}(v) \rangle = \langle \frac{d}{dt}(exp_p(v)) \Big|_{t=0}, \frac{d}{dt}(exp_p(v)) \Big|_{t=0} \rangle$$
$$= \langle \frac{d}{dt}(\gamma(t, p, v)) \Big|_{t=0}, \frac{d}{dt}(\gamma(t, p, v)) \Big|_{t=0} \rangle = \langle v, v \rangle.$$

We now separate w into its tangential, and normal component to v.

(ii)
$$\langle (dexp_p)_{\nu}(\nu), (dexp_p)_{\nu}(w_N) \rangle = 0$$

We define the curve u as $u: [-\varepsilon, \varepsilon] \times [0, 1] \to T_p M$, $(s, t) \mapsto tv + tsw_N$. It follows, u(0,1) = v, $\frac{\partial u}{\partial t}(s,t) = v + sw_N$, $\frac{\partial u}{\partial s}(0,t) = tw_N$. Furthermore, we consider the parametrized surface

 $f: [-\varepsilon, \varepsilon] \times [0, 1] \to M, (s, t) \mapsto exp_{v}(tv + tsw_{N}).$

Under this construction;

$$(dexp_p)_v(v) = (dexp_p)_{u(0,1)} \left(\frac{\partial u}{\partial t}(0,1) \right) = \frac{\partial}{\partial t} exp_p \circ u(s,t) \Big|_{t=1,s=0}$$
$$= \frac{\partial f}{\partial t}(0,1),$$

$$(dexp_p)_{\nu}(w_N) = (dexp_p)_{u(0,1)} \left(\frac{\partial u}{\partial s}(0,1) \right) = \frac{\partial}{\partial s} exp_p \circ u(s,t) \Big|_{t=1,s=0}$$
$$= \frac{\partial f}{\partial s}(0,1),$$

Hence,

$$\langle (dexp_p)_v(v), (dexp_p)_v(w_N) \rangle = \langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial s} \rangle (0, 1)$$

(iii) $\left. \frac{\partial}{\partial t} \left\langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial s} \right\rangle \right|_{(0,t)} = 0$

We are verifying that the above scalar product is actually independent on the variable t, so that we can conclude that $\langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial s} \rangle (0,1) = 0$ through the property $\lim_{t \to 0} \frac{\partial f}{\partial s} (0,t) = \lim_{t \to 0} (dexp_p)_{tv}(tw_N) = 0.$

Since the map $t \mapsto f(s,t)$ is geodesic for all s and t, $\frac{\partial}{\partial t} \langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial s} \rangle = \langle \frac{\partial}{\partial t}, \frac{\partial}{\partial t}, \frac{\partial}{\partial t}, \frac{\partial}{\partial t}, \frac{\partial}{\partial t}, \frac{\partial}{\partial s} \rangle = \langle \frac{\partial}{\partial t}, \frac{\partial}{\partial s}, \frac{\partial}{\partial t}, \frac{\partial}{\partial t},$

And since the map $t \mapsto f(s,t)$ is geodesic, the function $t \mapsto \langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial t} \rangle$ is constant. Thus $\frac{\partial}{\partial s} \langle \frac{\partial f}{\partial t}, \frac{\partial f}{\partial t} \rangle \Big|_{s=0} = \frac{\partial}{\partial s} \langle v + sw_N, v + sw_N \rangle \Big|_{s=0} = 2 \langle v, w_N \rangle = 0.$

(i),(ii), and (iii) yield us to complete the proof of the lemma with the bilinearity of the scalar product.

It is said that $U = exp_p V$ is a <u>normal neighborhood</u> of p, if exp_p is a diffeomorphism on a neighborhood V of the origin in $T_p M$. $B_{\varepsilon}(p) = exp_p B_{\varepsilon}(0)$, a <u>normal ball</u> (or a geodesic ball) if the closure of epsilon ball is in such V. Moreover, the Gauss lemma gives us that the n<u>ormal</u> <u>sphere</u> $S_{\varepsilon}(p) = \partial B_{\varepsilon}(p)$ is a hypersurface in the manifold M, which is orthogonal to the geodesics starting from p. Further, the geodesics in $B_{\varepsilon}(p)$ with starting point p are called <u>radial geodesics</u>.

2. The minimizing property of geodesics.

In this section we will observe that geodesics locally minimize the arc length. Namely,

Proposition 2. Let $p \in M, U = exp_pV, B = B_{\varepsilon}(p)$. Let $\gamma: [0,1] \to B$ be a geodesic segment with $\gamma(0) = p$, and $c: [0,1] \to M$ be any piecewise differentiable curve with $c(0) = \gamma(0), c(1) = \gamma(1)$. Then it holds for γ and $c, \ell(\gamma) \leq \ell(c)$. The equality holds if and only if $c([0,1]) = \gamma([0,1])$.

Proof. w.l.o.g. suppose that $c([0,1]) \subset B$. Otherwise cut c into parts along the boundary of B and be parametrized by [0,1]. To apply the Gauss lemma we shall find a parametrized surface f, such that $f(\gamma(t), t) = exp_p(\gamma(t) \cdot v(t))$, where $t \to v(t)$ a curve in T_pM , |v(t)| = 1, and $\gamma: (0,1] \to \mathbb{R}$ is a positive piecewise differentiable function. Simple calculus gives us, except for some singularities,

$$\frac{dc}{dt} = \frac{\partial f}{\partial \gamma} \frac{d\gamma}{dt} + \frac{\partial f}{\partial t}.$$

Applying the Gauss lemma yields, $\left\langle \frac{\partial f}{\partial \gamma}, \frac{\partial f}{\partial t} \right\rangle = 0$. For $\left| \frac{\partial f}{\partial \gamma} \right| = 1$,

$$\left|\frac{dc}{dt}\right|^{2} = \left|\frac{d\gamma}{dt}\right|^{2} + \left|\frac{\partial f}{\partial t}\right|^{2} \ge \left|\frac{d\gamma}{dt}\right|^{2},$$

as,

$$\int_{\varepsilon}^{1} \left| \frac{dc}{dt} \right| dt \ge \int_{\varepsilon}^{1} \left| \frac{d\gamma}{dt} \right| dt \ge \int_{\varepsilon}^{1} \frac{d\gamma}{dt} dt \ge \gamma(1) - \gamma(\varepsilon).$$

Taking $\varepsilon \to 0$ shows what it was claimed. If the equality holds for some *c*, then $\left|\frac{\partial f}{\partial \gamma}\right| = 0$, which let v(t) be constant, meaning that the curve is rescaled form of γ .

We have now reached that there is a piecewise differentiable curve which locally minimizes

the arc length. We shall further prove that this curve is a geodesic by showing the existence of normal neighborhoods.

Theorem 3. For any p in M, there exist a neighborhood W of p, which is a normal neighborhood of each of its points. In other words, $\forall p \in M, \exists W \subset M, \delta > 0$, such that $\forall q \in W$, exp_q is a diffeomorphism on $B_{\delta}(0) \subset T_q M$ and $exp_q(B_{\delta}(0)) \supset W$.

Proof. We shall prove this theorem in following manner.

- (i) Construct a local diffeomorphism
- (ii) Applying the inverse function theorem. For proof of this theorem, see the script of Analysis 2, Prof. Knüpfer, SS2014.

Let $\varepsilon > 0$, V a neighborhood of $p \in M$, $\Omega = \{(q, v) \in TM; q \in V, v \in T_qM, |v| < \varepsilon\}$. Define $F: \Omega \to M \times M$, $(q, v) \mapsto (q, exp_q v)$. F is then a local diffeomorphism around (p, 0). Indeed, $(dexp_p)_0 = I$, and the matrix $dF_{(p,0)}$ is $\begin{pmatrix} I & I \\ 0 & I \end{pmatrix}$. Thus we have a local diffeomorphism. From the inverse function theorem, there exists a neighborhood $\Omega' \subset \Omega$ of (p, 0), and a neighborhood W' of (p, p), so that $F: \Omega' \to W'$ is bijective and differentiable. By choosing $\Omega' = \{(q, v) \in TM; q \in V' \subset V, v \in T_qM, |v| < \delta\}$ and W such that $W \times W \subset W'$, we get the assertion.

Remark: It is said that W is a totally normal neighborhood of $p \in M$. As we have seen that there is a unique minimizing geodesic γ with $\ell(\gamma) < \delta$, for given two points of W. By having this theorem we can conclude that there is a unique v in $T_{\sigma}M$, for (σ, τ) in W, such that $\gamma'(0) = v$.

Corollary 4. A piecewise differentiable curve $\gamma: [a, b] \to M$ with parameter proportional to arc length is a geodesic, if for any other piecewise differentiable curve $c: [a', b'] \to M, c(a') = \gamma(a)$ and $c(b') = \gamma(b)$, holds $\ell(\gamma) \leq \ell(c)$.

Proof. We shall prove with the compactness argument. There exists a pathwise connected compactum K, with $K^{\circ} \neq \emptyset$. Let W be a totally normal neighborhood of $\gamma(t)$, $t \in K$. Then the inclusion $\gamma(K) \subset W$ holds. Consider the restriction of $\gamma_K: K \to W$. Since $\gamma_K(K)$ is in a normal ball, it has equal length of a radial geodesic in W. From the minimizing property, γ_K is a geodesic. Furthermore, since it holds for all $t \in [a, b]$ that $\frac{d}{dt} \langle \frac{d\gamma}{dt}, \frac{d\gamma}{dt} \rangle = 0$, which implies $C := \langle \frac{d\gamma}{dt}, \frac{d\gamma}{dt} \rangle = const$. Thus, if C is non-zero, γ must be a regular curve. (If C is equal to zero, γ degenerates to a point in M.)

In following example, we are using this corollary above, to determine the geodesics in so called the Lobatschevski plane, whilst the geodesics is being mapped to geodesics by isometries of a Riemannian manifold.

Example: Given that G is the upper half-plane in two dimensional Euclid space with the Riemannian metric $g_{11} = g_{22} = \frac{1}{y^2}$, $g_{12} = g_{21} = 0$. We are claiming that the segment $\gamma: [a, b] \rightarrow G, a > 0, \gamma(t) = (0, t)$ is the image of a geodesic under an isometry. [Indeed, for any $c: [a, b] \rightarrow G, t \mapsto (x(t), y(t))$ with c(a) = (0, a) and c(b) = (0, b), it holds that

$$\ell(c) = \int_{a}^{b} \left| \frac{dc}{dt} \right| dt = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dx}{dt}\right)^{2}} \frac{dt}{y} \ge \int_{a}^{b} \left| \frac{dy}{dt} \right| \frac{dt}{y} \ge \int_{a}^{b} \frac{dy}{dt} \frac{dt}{y} \ge \int_{a}^{b} \frac{dy}{dt} \frac{dt}{y} \ge \ell(\gamma).$$

Hence γ is the minimizer of arc length, by the corollary it is a geodesic.]

To this purpose, we take the möbius transformations Φ_{abcd} : $\mathbb{C} \cong \mathbb{R}^2 \to \mathbb{C}$ as our isometries, given by $z \mapsto \frac{az+b}{cz+d}$, ad - bc = 1. For details, see the script of Funktionentheorie, Prof. Kohnen. These transformations give us rays or half circles, which vary on the values of *a*,*b*,*c* and *d*.

3. Convex neighborhoods

We have observed that every point in a Riemannian manifold has a totally normal neighborhood. Still, there are cases that our geodesics are not completely lying in a certain totally normal neighborhood. In this section we will see that a totally normal neighborhood W can be chosen on a Riemannian manifold, so that W is becoming strongly convex.

Definition 5. A subset $S \subset M$ is <u>strongly convex</u> if for any two points $q_1, q_2 \in \overline{S}$ there exists unique minimizing geodesic γ such that $(\gamma([q_1, q_2]))^{\circ} \subset S$.

Lemma 6. For any $p \in M$, there is an upper boundary c for radius r, such that any geodesic in M that is tangent at $q \in M$ to $S_r(p) = \partial B_r(p)$ stays out of the $B_r(p) = exp_p B_r(0)$.

Proof. Let *W* be a totally normal neighborhood of $p \in M$. Since all geodesics in *W* can be considered to have the velocity one through the natural parametrization, it is enough to prove with the unit tangent bundle $T_1W = \{(q, v); q \in W, v \in T_qM, |v| = 1\}$.

Consider the differentiable mapping $\gamma: (-\varepsilon, \varepsilon) \times T_1 W \to M$, where $t \to \gamma(t, q, v)$ be the geodesic with the initial condition at $t = 0, \gamma$ passes $q = \gamma(0, q, v)$, |v| = 1. Let $u(t, q, v) = exp_p^{-1}(\gamma(t, q, v))$ and define $F: (-\varepsilon, \varepsilon) \times T_1 W \to \mathbb{R}, F(t, q, v) = |u(t, q, v)|^2$. From the constructions follows $\frac{\partial F}{\partial t} = 2 \langle \frac{\partial u}{\partial t}, u \rangle, \frac{\partial^2 F}{\partial t^2} = 2 \langle \frac{\partial^2 u}{\partial t^2}, u \rangle + 2 \left| \frac{\partial u}{\partial t} \right|^2$. Further, we choose our radius r > 0, so that $B_r(p) = exp_p B_r(0) \subset W$. Observe that if γ is tangent to $S_r(p) =$ $\partial B_r(p)$, at $q = \gamma(0, q, v)$, then $\frac{\partial F}{\partial t}\Big|_{(0,q,v)} = \langle \frac{\partial u}{\partial t}, u \rangle\Big|_{(0,q,v)} = 0$, from the Gauss lemma. We are showing that F has a strict minimum at (0, q, v), for some enough small radius r. For starters we observe for q = p, we have $u(t, p, v) = exp_p^{-1}(\gamma(t, p, v)) = tv$, as well as $\frac{\partial^2 F}{\partial t^2}\Big|_{(0,p,v)} = 2 \left|\frac{\partial}{\partial t}(tv)\right|^2 = 2|v|^2 = 2 > 0$. Thus there exist a neighborhood $\Omega' \subset W$ of p such that $\frac{\partial^2 F}{\partial t^2}\Big|_{(0,q,v)} > 0$, for all $q \in \Omega', v \in T_q M$, |v| = 1. Now choose an upper boundary c s.t. $exp_p B_c(0) \subset \Omega'$. Since a strict minimum gives us the minimizer for distance between p and to a point p_γ that is moving along the geodesic γ , with minimizing property there is another geodesic in $B_c(p) = exp_p B_c(0)$, joining p and p_γ , which is tangent to $S_r(p) = \partial B_r(p)$ at $q = \gamma(0, q, v)$, as claimed.

Proposition 7. (Convex neighborhoods). For any $p \in M$, there is a number $\beta > 0$ such that the normal ball $B_{\beta}(p)$ is strongly convex.

Proof. Let *c* be the upper boundary given in the above lemma for a $p \in M$. Choose $\frac{c}{2} > \delta > 0$ and $W \ s.t. \ \forall q \in W$, exp_q is a diffeomorphism on $B_{\delta}(0) \subset T_q M$ and $exp_q(B_{\delta}(0)) \supset W$. We shall prove that $B_{\beta}(p)$ is strongly convex for $\beta < \delta : B_{\beta}(p) \subset W$. Given that two random points $q_1, q_2 \in \overline{B_{\beta}(p)}$, let γ be the geodesic with $\ell(\gamma) < 2\delta < c$, joining q_1 and q_2 . Assume that $(\gamma([q_1, q_2]))^{\circ} \not\subset B_{\beta}(p)$ i.e. $B_{\beta}(p)$ is not strongly convex. Then there is a point x in $(\gamma([q_1, q_2]))^{\circ}$, with the maximum distance r from q. Hence for enough small $\varepsilon > 0, B_{\varepsilon}(x) \cap \overline{B_r(p)} \neq \emptyset$, which is contradiction to the lemma 6.

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